Type 3738-20 Electronic Limit Switch

with optional integrated solenoid valve
for valves used in on/off applications

Mounting and Operating Instructions

EB 8390 EN

Firmware version 1.12

Edition December 2013

CE Ex certified

Definition of the signal words used in these mounting and operating instructions

DANGER!
indicates a hazardous situation which, if not avoided, will result in death or serious injury.

WARNING!
indicates a hazardous situation which, if not avoided, could result in death or serious injury.

NOTICE
indicates a property damage message.

Note:
Supplementary explanations, information and tips

1 Important safety instructions 6
2 Article code 7
3 Design and principle of operation 8
3.1 Versions 11
3.2 Communication 12
3.3 Safety-related information 12
4 Technical data 14
4.1 Electronic limit switch 14
4.2 Solenoid valve 16
5 Attachment 17
5.1 Accessories 18
5.2 Attachment to linear actuators 19
5.2.1 Preparations 19
5.2.2 Attachment 20
5.3 Attachment to rotary actuators 22
5.3.1 Preparations 24
5.3.2 Attachment 26
6 Connections 28
6.1 Pneumatic connections 28
6.2 Supply pressure 28
6.3 Electrical connection 29
7 Operator controls and readings 33
7.1 Rotary pushbutton 33
7.2 SAMSON SSP interface 33
7.3 Operating structure 34
8 Start-up 38
8.1 Adapting the display direction 38
8.2 Verifying readings on display 38
8.3 Determining the actuator type 39
8.4 Determining the direction of action 40
8.5 Determining the switching function of contacts 40

8.6 Adjusting the limit contacts 40
8.7 Initialization 41
8.7.1 Start automatic initialization 42
8.7.2 Start manual initialization 43
8.8 Replacing an electronic limit switch 44
8.9 Zero/end position calibration 44
8.10 Reset to default settings 45
9 Operation 46
9.1 Lock operation 46
9.2 Partial stroke test (PST) 46
9.2.1 Defining the PST target range 49
9.2.2 Starting the partial stroke test 49
9.2.3 Configuration example based on PTO direction of action 50
9.3 Testing the contacts 53
9.4 Testing the solenoid valve 53
9.5 Faults 54
9.5.1 Status messages 54
9.5.2 Error messages 54
9.5.3 Confirming status and error messages 55
10 Maintenance, calibration and work on equipment 55
10.1 Maintenance 55
11 Servicing explosion-protected devices 56
12 Firmware update (serial interface) 56
13 Parameter list 57
13.1 Status messages 61
13.2 Error messages 63
14 Dimensions in mm 65
Index 74
Assignment based on the direction of action 79

Firmware revisions	
Firmware	Revisions
1.12	**Changes to parameters and error messages (see section 13)** • Parameters renumbered due to parameters being added or removed. Removed parameters: – 'PST initialization' (the partial stroke test no longer needs to be initialized). – Info: Rotary motions New parameters: – 'Actuator type' (rotary or linear actuator). See section 8.3. – 'Switching function of contacts' (NO or NC contact). See section 8.5. • Error messages renumbered due to error messages being removed. Removed error messages: – 'PST target range not reached' – 'PST target range exceeded' • The new parameter 'Actuator type' as well as the 'Actuator's direction of action' parameter are locked after the electronic limit switch has been initialized. See sections 8.3 and 8.4. • The actuator transit time monitoring (F4) depends on the value adjusted in 'Status readout for actuator transit time (P13). This is adjustable between 0 (OFF) and 1800 s. • The dead time is already included in the information parameters 'Actuator transit time when the solenoid valve is de-energized' (P22) and 'Actuator transit time when the solenoid valve is energized' (P23). • The monitoring of the rotary motion counter can be deactivated by configuring 'Maximum rotary motions' (P26) = OFF. **Changes to the partial stroke test (PST) (see section 9.2)** • The minimum pulse length at contact C is three seconds during partial stroke testing. • The PST target range is made up of 'PST step end (P14) ± ½ 'PST tolerance band' (P15). • After a successfully completed partial stroke test, the assessment of the transit times when the solenoid valve is de-energized' and energized ('PST transit time when the solenoid valve is de-energized and 'PST transit time when the solenoid valve is energized'). In firmware version 1.01, only the duration of the entire test could be read. • In the TROVIS-VIEW software, a diagram plotting the valve position against time while the solenoid valve is de-energized and energized is shown (256 measuring points). The data can be read out by connecting the device at the SSP interface to a PC.

1 Important safety instructions

For your own safety, follow these instructions concerning the mounting, start up and operation of the electronic limit switch:

– The device is to be mounted, started up or operated only by trained and experienced personnel familiar with the product. According to these mounting and operating instructions, trained personnel is referred to as individuals who are able to judge the work they are assigned to and recognize possible dangers due to their specialized training, their knowledge and experience as well as their knowledge of the applicable standards.
– Explosion-protected versions of this device are to be operated only by personnel who has undergone special training or instructions or who is authorized to work on explosion-protected devices in hazardous areas.
– Any hazards that could be caused by moving parts are to be prevented by means of the appropriate measures.
– For use within hazardous areas, the Special Conditions mentioned in the EC type examination certificate and its addenda must be observed.
– If inadmissible motions or forces are produced in the pneumatic actuator as a result of the supply pressure level, it must be restricted using a suitable supply pressure reducing station.

To avoid damage to any equipment, the following also applies:

– Proper shipping and storage are assumed.
– Do not ground electric welding equipment near to the electronic limit switch.

Note:
The device with a CE marking fulfills the requirements of the Directive 2004/108/EC.

2 Article code

Electronic Limit Switch	**Type 3738-20-**	x	x	x	1	x	0	0	x	x	x	x	0	x
With LCD														
Explosion protection														
Without		0	0	0										
ATEX: II 2G Ex ia IIC T6; II 2D Ex IIIC T80°C IP 66		1	1	0										
ATEX: II 2G Ex eb[ia] IIC T4; II 2D Ex tb IIIC T80°C IP 66		3	1	0		0								
GOST: 1Ex ia IIC T6/T5/T4 Ga X; Ex tb IIIC T80°C Db X		1	1	3										
GOST: 1Ex e [ia] IIC T4 Gb X; Ex tb IIIC T80°C Db X		3	1	3										
Solenoid valve														
External						0								
Integrated						4								
Company version														
SAMSON									0					
AIR TORQUE									1					
Housing														
Standard aluminum, black structured, RAL 9005										1				
Cover														
Gray beige											0			
Black											1			
Silver gray											3			
Safety approval (refer to section 3.3)														
TÜV/IEC 61508												2		
Special applications														
Without													0	

3 Design and principle of operation

The Type 3738-20 Electronic Limit Switch can replace conventional solenoid valves and limit switches used for the automation of on/off valves without the need to change the wiring or signal level. Major features of the electronic limit switch include:

– Unification of the functions featured in limit switches and a solenoid valve in one housing
– Power supplied in a two-wire system from the connection of contact A, without the need for an additional power supply
– Non-contact sensing of the rotation angle by a magnetoresistive sensor system
– Integrated diagnostics with partial stroke testing (PST)
– Suitable for use in safety-instrumented systems up to SIL 2 (single device) and SIL 3 (redundant configuration). Refer to section 3.3 on page 12.

Fig. 1: *Valve assembly with electronic limit switch (version with integrated solenoid valve)*

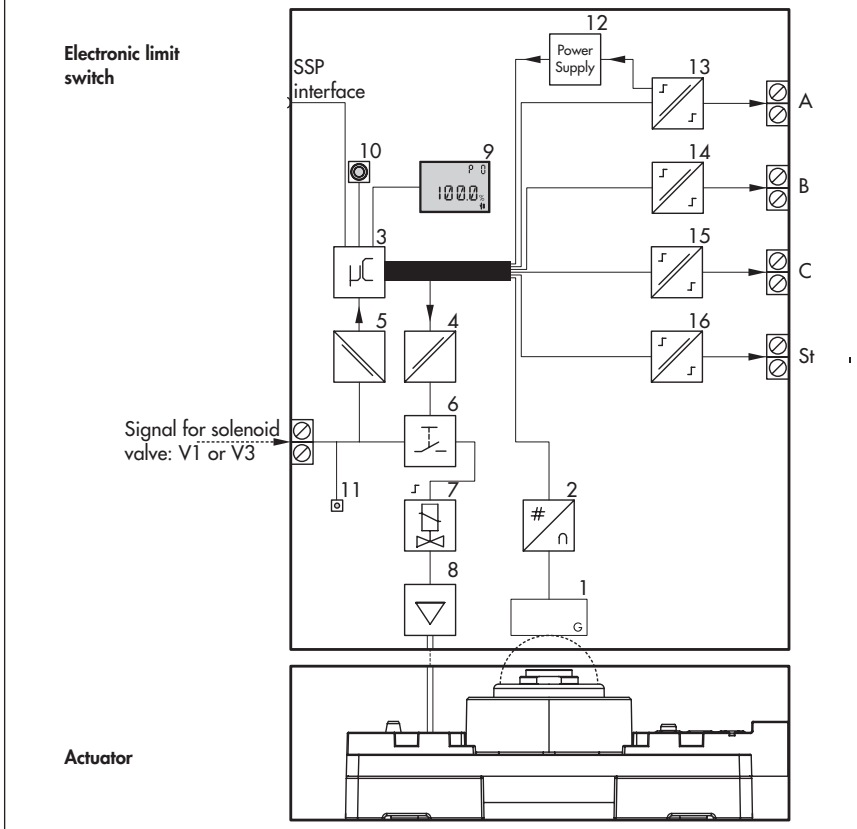
Fig. 2 and Fig. 3

The electronic limit switch is designed for attachment to linear and rotary actuators. The travel is measured without contact using a magnet (on a screw) positioned centrically on the actuator shaft. The screw with magnet does not need to be adjusted. The AMR (anisotropic magnetoresistive) sensor located in the device together with the measuring electronics (1) can detect the directional change of the applied magnetic field and, as a result, sense the movement of the actuator.

The actuator is actuated by a solenoid valve (7) which converts the binary signal issued by electric control equipment (6) into a binary pressure signal.

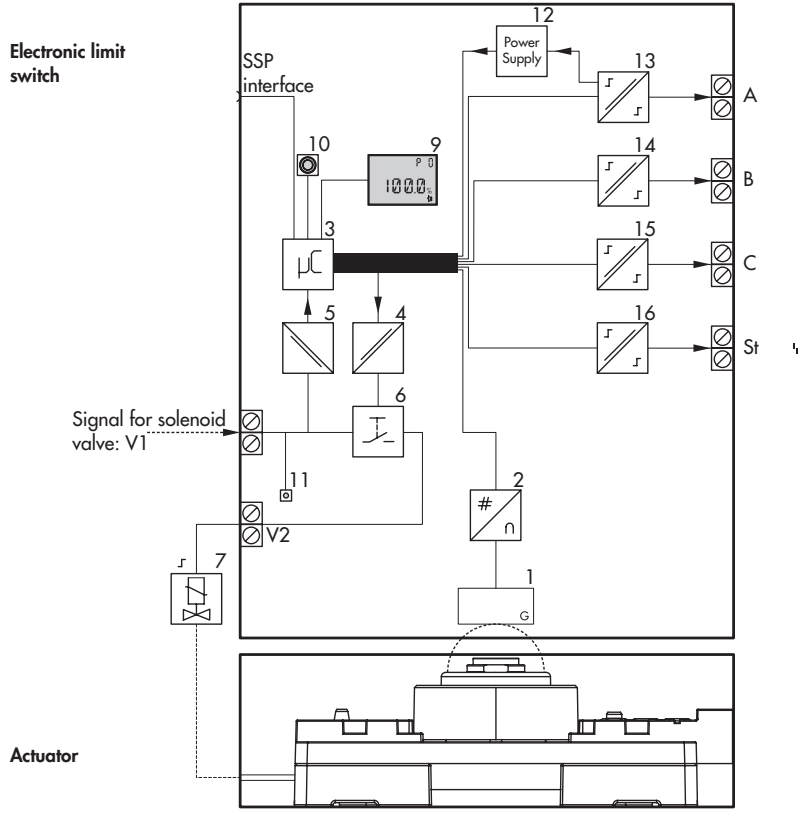
The electronic limit switch has four NAMUR contacts: the limit switch for fail-safe position (contact A, 13) and the limit switch for operating position (contact B, 14) issue a limit signal when the valve reaches the corresponding end position. Contact C indicates that a third limit has been reached or that the target range has been reached during the partial stroke test. The switching response of the contacts can be adjusted within the travel range. The fault alarm contact St (16) indicates the generation of any status and error messages.

An electronic limit switch version for an external solenoid valve (Fig. 2) is available for higher air capacities required by large actuators. The principle of operation is the same.



1	AMR sensor with electronics	9	Display
2	A/D converter	10	Rotary pushbutton (on-site operation)
3	Microcontroller	11	LED for solenoid valve
4	Electrical insolation	12	Internal supply
5	Electrical insolation	13	NAMUR contact A (limit switch for fail-safe position)
6	Actuation of solenoid valve	14	NAMUR contact B (limit switch for operating position)
7	Solenoid valve	15	NAMUR contact C (signal when PST target range reached)
8	Air capacity booster	16	NAMUR contact St (fault alarm contact)

Fig. 2: *Schematic diagram – Type 3738-20-xxx1400xxx000 Electronic Limit Switch with integrated solenoid valve*



1 AMR sensor with electronics
2 A/D converter
3 Microcontroller
4 Electrical insolation
5 Electrical insolation
6 Actuation of solenoid valve
7 Solenoid valve
9 Display
10 Rotary pushbutton (on-site operation)
11 LED for solenoid valve
12 Internal supply
13 NAMUR contact A (limit switch for fail-safe position)
14 NAMUR contact B (limit switch for operating position)
15 NAMUR contact C (signal when PST target range reached)
16 NAMUR contact St (fault alarm contact)

Fig. 3: *Schematic diagram – Type 3738-20-xxx1**0**00xxxx00 Electronic Limit Switch with external solenoid valve*

NAMUR contacts A, B, C

The contacts can be configured as either NO or NC contacts. See Fig. 4 and section 8.5.

NAMUR contact St

This contact is a NC contact.

3.1 Versions

Type 3738-20-xxx1400xxx000 Electronic Limit Switch with integrated solenoid valve

The electronic limit switch with integrated solenoid valve form a compact unit together with a pneumatic actuator, which is easy to mount. The 3/2-way or 5/2-way function of the solenoid valve is selected by changing the position of a molded seal.

Based on VDI/VDE 3845, level 2, its version can be mounted onto Pfeiffer Type 31b Rotary Actuators. The need for additional pneumatic connections is eliminated.

Type 3738-20-xxx1000xxxx00 Electronic Limit Switch for external solenoid valve

The electronic limit switch for an external solenoid valve allows switching capacities up to max. 18 W at 24 V DC, meaning all common solenoid valves, even the Ex e versions, can be combined with the electronic limit switch. This version is suitable for rotary actuators according to VDI/VDE 3845, level 1. See Fig. 4.

Changes to the electronic limit switch's settings do not effect the external solenoid valve.

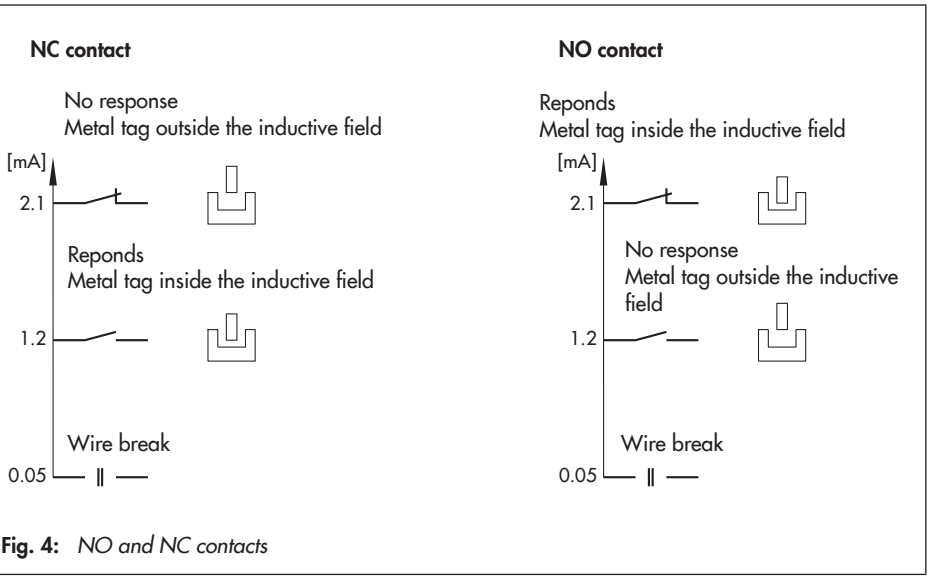


Fig. 4: *NO and NC contacts*

3.2 Communication

The electronic limit switch can be configured with SAMSON's TROVIS-VIEW Configuration and Operator Interface.
The electronic limit switch has for this purpose a SAMSON SSP interface to allow the RS-232 or USB port of a computer to be connected to it over a serial interface adapter cable.
The TROVIS-VIEW software enables the user to easily configure the electronic limit switch as well as view and document process parameters on a computer.

See Table 1 on page 18 for order numbers.

Note:
TROVIS-VIEW provides a uniform user interface that allows users to configure and parameterize various SAMSON devices using device-specific database modules. The Type 3738-20 device module can be downloaded free of charge from our website (www.samson.de) at Services > Software > TROVIS-VIEW. Further information on TROVIS-VIEW (e.g. system requirements) is available on our website and in the Data Sheet ▶ T 6661 EN.

3.3 Safety-related information

The Type 3738-20 Electronic Limit Switch was developed to meet the requirements stipulated in IEC 61508. The safety-related data are listed in the Manufacturer's Declaration HE 1163.
The conformity of the development process and the performed FMEDA as well as the statements in the Manufacturer's Declaration HE 1163 are certified by TÜV Rheinland Industrie Service GmbH in the Certificate 968/EL 485.01/09 dated 9 November 2009.

Type 3738-20-xxx1000xxxx00 in combination with an external solenoid valve

The forwarding of the switching voltage for the external solenoid valve by the Type 3738-20-xxx1000xxxx00 Electronic Limit Switch has the same quality as wiring and does not lead to a change in the safety-related data of the circuit.

Safety-related assumptions

Safety-related end position monitoring

All switching contacts of the Type 3738-20 Electronic Limit Switch behave as stipulated in IEC 60947-5-6 and are suitable for use in safety-instrumented systems up to SIL 2 (single device) and SIL 3 (redundant configuration) according to TÜV/IEC 61508. The contacts can be used either as NC or NO contacts. Their switching states are indicated according to IEC 60947-5-6. Contact A is assigned to the end position for the fail-safe position (limit switch for fail-safe position). The fail-safe position is the end position to which the single-acting actuator is moved by the spring-return mechanism when the solenoid valve is de-energized.

Emergency venting

When the optional integrated solenoid valve is used, the electronic limit switch discharges its pneumatic output to the atmosphere when the solenoid valve is de-energized. This causes the mounted actuator to be vented. The function is suitable for use in safety-in-

strumented systems up to SIL 2 (single channel) and SIL 3 (redundant configuration) according to IEC 61508.

Note:
Safety-related end position monitoring and emergency venting work independently from one another to meet the device design requirements to conform with SIL.

Requirements

- Short mean time to repair compared to the average rate of demand
- Normal exposure to industrial environment and fluids
- The user is responsible for ensuring that the device is used as intended.

Useful lifetime

According to IEC 61508-2, section 7.4.9.5, a useful lifetime of 8 to 12 years can be assumed. Other values can be used based on the user's experience.

Notes concerning diagnostics

- A diagnostics are performed cyclically inside the device. Critical errors (device error E9) are indicated by contact B as wire breakage according to IEC 60947-5-6. Existing errors must be remedied as described in these Mounting and Operating Instructions. If this is not possible, the electronic limit switch must not be used in safety loops.
- The proper functioning of the display can be verified over **P3** parameter. Refer to section 8.2.
- The correct setting of all parameters must be verified before every start-up.

Proof testing

All switching contacts need to be activated for the proof test. This can be done by:
- Using the mounted actuator to move the valve to the end position
- Simulating the outputs using **P19** parameter. Refer to section 9.4.

During the proof test, check that the outputs switch properly.

Intended use

The specifications and information in the data sheet and in these instructions must be observed.

Note concerning diagnosis of connected solenoid valve and actuator

The diagnostics functions performed in the device, e.g. actuator transit time monitoring, are suitable for diagnosis of connected devices, such as solenoid valve, pneumatic actuator and valve.

Repairs

Devices which are used in safety-instrumented systems must be repaired by the manufacturer.

4 Technical data

4.1 Electronic limit switch

Electronic Limit Switch Type		**3738-20-xxx1400xxx000**	**3738-20-xxx1000xxxx00**
Version		With integrated solenoid valve	With external solenoid valve
Permissible range of rotation		Min.: 0 to 30° Max.: 0 to 170°	
Communi-cation	Local communication	SAMSON SSP interface with serial interface adapter	
	Software	TROVIS-VIEW with database module 3738-20	
Supply air	Supply air	2.4 to 8 bar	Same as specifications of the solenoid valve manufacturer
	Air quality	Acc. to ISO 8573-1 Max. particle size and density: Class 4 Oil content: Class 3 Moisture and water: Class 3 Pressure dew point: at least 10 K beneath the lowest ambient temperature to be expected	
Electric power supply		Powered over contact A acc. to IEC 60947-5-6 (e.g. NAMUR isolating switch amplifier)	
Permissible ambient temperature		–25 to 80 °C	–40 to 80 °C
The limits specified in the examination certificate additionally apply.		Metal cable glands must be used for ambient temperatures below –20 °C.	
Influences	Temperature	±0.7 %/90° angle above the permissible temperature range	
	Influence of vibrations	≤ 0.25 % up to 2500 Hz and 4 g according to IEC 770	
Electromagnetic compatibility		Complying with EN 61000-6-2, EN 61000-6-3, EN 61326-1 and NAMUR Recommendation NE 21	
Electrical connections		Four M20 x 1.5 cable glands for 6 to 12 mm clamping range, screw terminals for 0.2 to 2.5 mm² wire cross-sections	
Explosion protection			
	Type 3738-20-000…	Without	
ATEX:	Type 3738-20-110…	II 2G Ex ia IIC T6; II 2D Ex ia IIIC T80°C IP66	
ATEX:	Type 3738-20-310…	II 2G Ex eb[ia] IIC T4; II 2D Ex tb IIIC T80°C IP66	
GOST:	Type 3738-20-113…	1Ex ia IIC T6/T5/T4 Ga X; Ex tb IIIC T80°C Db X	
GOST:	Type 3738-20-313…	1Ex e [ia] IIC T4 Gb X; Ex tb IIIC T80°C Db X	
NEPSI:	Type 3738-20-812...	Ex nL IIC T4~T6 Gc; Ex nA IIC T4~T6 Gc; DIP A22 Ta, T4~T6	

Electronic Limit Switch Type		3738-20-xxx1400xxx000	3738-20-xxx1000xxxx00
Version		With integrated solenoid valve	With external solenoid valve
Degree of protection		IP 66	
Safety approval	Safety-related end position monitoring	The limit switches are suitable for use in safety-instrumented systems up to SIL 2 (single channel) and SIL 3 (redundant configuration) according to IEC 61508. For further details, refer to section 3.3 Safety-related information.	
	Emergency venting	See section 3.3 Safety-related information.	Same as specifications of the solenoid valve manufacturer
Materials	Housing	Die-cast aluminum EN AC-AlSi12(Fe) (EN AC-44300) acc. to DIN EN 1706, powder paint coated	
	Housing cover	PC	
	Cover gasket	PU	
	Indicator wheel	PC	
	Magnet material	Hard ferrite	
Weight		Approx. 1.2 kg	Approx. 1.0 kg
Contacts · Only for connection according to IEC 60947-5-6, reverse polarity protection, galvanic isolation			
Switching function		NC contact	NO contact
Switching contacts	No response/no fault	≥ 2.1 mA	≤ 1.2 mA
	Response/fault indication	≤ 1.2 mA	≥ 2.1 mA
Hysteresis		1 %	
Contacts	Contact A Limit switch for fail-safe position (solenoid valve de-energized)	PTO (power to open): Responds when the valve moves through the switching contact towards the lower end position (P7) PTC (power to close): Responds when the valve moves through the switching contact towards the upper end position (P8)	
	Contact B Limit switch for operating position (solenoid valve energized)	PTO (power to open): Responds when the valve moves through the switching contact towards the upper end position (P8) PTC (power to close): Responds when the valve moves through the switching contact towards the lower end position (P7) Signal for wire breakage according to IEC 60947-5-6	
	Contact C Signal when target range reached during partial stroke test	Responds when the valve reaches the PST target range* * PST target range = 'PST step end' (P14) ± ½ 'PST tolerance band' (P15)	

Electronic Limit Switch Type		3738-20-xxx1400xxx000	3738-20-xxx1000xxxx00
Version		With integrated solenoid valve	With external solenoid valve
Contacts	Contact C Limit contact for intermediate position	PTO (power to open): Responds when the valve moves through the switching contact towards the operating position (P14) PTC (power to close): Responds when the valve moves through the switching contact towards the fail-safe position (P14)	
	Contact St Fault alarm contact	Responds when a status message or error message is generated (always NC contact)	
Current specifications when contact A is not connected		Contact B: I = 50 µA (wire breakage) Contact C: I = 1.2 mA Contact St: I = 1.2 mA	

4.2 Solenoid valve

Integrated solenoid valve (Type 3738-20-xxx1400xxx000)		
Current draw		$I = \frac{2.7 * U}{3650\,\Omega} - 3.325$ mA (corresponding to 14.4 mA at 24 V)
Version		3/2-way or 5/2-way function Function determined by the position of the molded seal
K_{VS} coefficient		0.32
Service life		1,000,000 switching cycles
Temp. range (operation)		–25 to +80 °C
Switching voltage	Nom. voltage	24 V DC, reverse polarity protection, galvanic isolation
	Signal 0	When the voltage falls below 15 V DC
	Signal 1	Min. 18 V DC
Switching capacity		24 V DC, 15.2 mA (0.36 W)
Duty cycle		100 %
Static destruction limit		32 V DC

External solenoid valve (Type 3738-20-xxx1000xxxx00)		
Read manufacturer's specifications!		
24 V DC, max. 18 W		
Switching voltage	Signal 0	When the voltage falls below 15 V DC
	Signal 1	Min. 18 V DC
Static destruction limit		32 V DC

5 Attachment

DANGER!

– ***Electrostatic charging***

Due to the high surface resistance of the enclosure cover ($R_{Isol.} \geq 10^9\ \Omega$), installation and maintenance on the equipment must be performed in such a way that electrostatic charging cannot occur.

– ***Mechanical effects***

In areas where damage to the housing can be expected due to mechanical influences, the housing must be protected by an additional cover.

– ***Combustible dust atmospheres***

The electronic limit switch complies with the requirements for type of protection Ex tb as the enclosure (housing) is designed according to EN 60079-31. The housing has the degree of protection IP 66 according to IEC 60529.

WARNING!

Mount the electronic limit switch, keeping the following sequence:

– *Mount the electronic limit switch on the actuator. Refer to section 5.2 and 5.3.*
– *Connect the supply air. Refer to section 6.1 and 6.2.*
– *Connect the electrical power. Refer to section 6.3.*
– *Perform the start-up settings. Refer to section 8.*

NOTICE

Observe the following instructions to avoid damaging the electronic limit switch:

– *Use only the accessories listed in the Table 1 to mount the electronic limit switch!*
– *Observe the shaft height of the actuator on mounting the electronic limit switch on rotary actuators!*

5.1 Accessories

Table 1: *Accessories*

			Order no.
Attachment to linear actuators (NAMUR attachment)	Version with integrated solenoid valve	G ¼	1402-0540
	Version with integrated solenoid valve	¼ NPT	1402-0541
	Version for external solenoid valve	G ¼	1402-0542
	Version for external solenoid valve	¼ NPT	1402-0543
	Plus mounting parts for Type 3271 Actuator		
	Version up to 700 cm²		–
	1400-60 and 2800-120 versions		1402-0544
	2800-30 and 2800-60 versions		1402-0545
Attachment to rotary actuators acc. to VDI/ VDE 3845, fixing level 1 (2010)	Attachment (20 mm shaft height)		1400-9859
	Attachment (30 mm shaft height)		1400-9860
	Attachment (50 mm shaft height)		1400-9861
	Attachment (50 mm shaft height, 88 mm shaft diameter), e.g. Pfeiffer Type 31b, size 2000		1402-0332
	Standard mounting platform (black)	G ¼	1380-1266
	Standard mounting platform (black)	¼ NPT	1380-1268
	Mounting platform with piping as required	G ¼	1380-1738
	Mounting platform with piping as required	¼ NPT	1380-1739
Cable glands (M20 x 1.5)	Nickel-plated brass		1880-4875
	Stainless steel 1.1305		8808-0160
	Version for Ex i: black plastic		8808-0180
	Version for Ex i: blue plastic		8808-0181
TROVIS-VIEW Configuration and Operator Interface software	TROVIS-VIEW with device module 3738-20 (free download from www.samson.de)		
	Serial interface adapter (SAMSON SSP interface to RS-232 port on a PC)		1400-7700
	Isolated USB interface adapter (SAMSON SSP interface to USB port on a PC)		1400-9740

5.2 Attachment to linear actuators

The electronic limit switch is mounted to linear actuators according to IEC 60534-6 (NAMUR attachment).

Required accessories: see Table 1

5.2.1 Preparations

Version with integrated solenoid valve (Type 3738-20-xxx1400xxx000) (Fig. 5)

1. Insert the molded seal (3) into the mounting unit (2) depending on the type of actuator (single-acting or double-acting).
2. Push the O-ring (3.1) onto the air duct of the molded seal (3).
3. Fasten the electronic limit switch (1) to the mounting unit (2) using the two screws mounted on the electronic limit switch as shown in Fig. 5.
4. Remove the stopper on the supply air port (SUPPLY, 2.1) of the mounting unit (2).

Version with external solenoid valve (Type 3738-20-xxx1000xxx00)

1. Fasten the electronic limit switch (1) to the mounting unit (2) using the two screws mounted on the electronic limit switch as shown in Fig. 5.

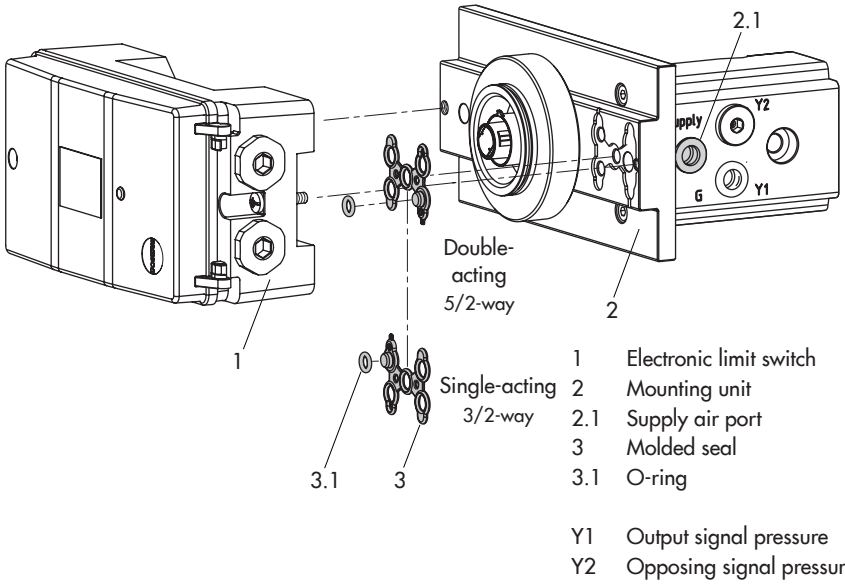


Fig. 5: *Preparations for mounting the electronic limit switch with integrated solenoid valve*

5.2.2 Attachment

Use the lever (5) underneath the mounting unit (2) and the pin (6) on the lever to adapt the electronic limit switch to the linear actuator used.

Table 2: *Travel table*

Actuator size [cm²]	Rated travel [mm]	Lever	Recommended pin position
120 to 350	15	M	35
700	15/30	M	50
1400	60	L	100
2800	120	XL	200
2800	30	M	50
2800	60	L/XL	100/200

The electronic limit switch is equipped with the lever M (pin position 35) as standard.

Levers L and XL are included in the mounting parts 1402-0544 or 1402-0545.

1. Select lever (5) according to Table 2.
2. Insert the follower pin (6) into the pin position according to Table 2 of the lever (5). Fasten tight using the washers and nuts (Fig. 6).
3. Place the lever (5) on the shaft of the mounting unit (2) and screw tight using the disk spring (5.1) and nut (5.2).
4. **Mounting to actuators with 120 to 700 cm² actuator areas (Fig. 7 1):**
   Fasten the follower plate (7.1) on the middle holes of the stem connector (9) of the actuator using the washers (7.2) and screws (7.3).

   Mounting to Type 3271 Actuators with 1400 and 2800 cm² actuator areas and with 200 mm rated travel (Fig. 7 2)
   Fasten the follower plate (7.4) on the outer holes to the stem connector (9) of the actuator using the screws (7.5).

   Mounting to Type 3271 Actuators with 2800 cm² actuator area and with 50, 100 or 200 mm rated travel (Fig. 7 3)
   Fasten the bracket (8) onto the stem connector (9) of the actuator using the screws (8.2).
   Fasten the follower plate (7.1) together with the pins (8.1) on the middle holes to the bracket (8) using the washers (7.2) and screws (7.3).
5. Fasten the mounting unit (2) on the actuator using the screw (4), making sure that the follower pin (6) comes to rest in the slot of the follower plate (7.1/7.4).
6. Electronic limit switch with integrated solenoid valve: connect supply air to supply air port (SUPPLY, 2.1).

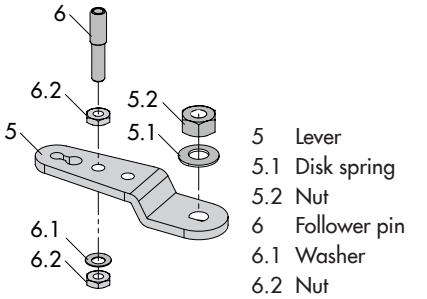


Fig. 6: *Fastening the follower pin on the lever*

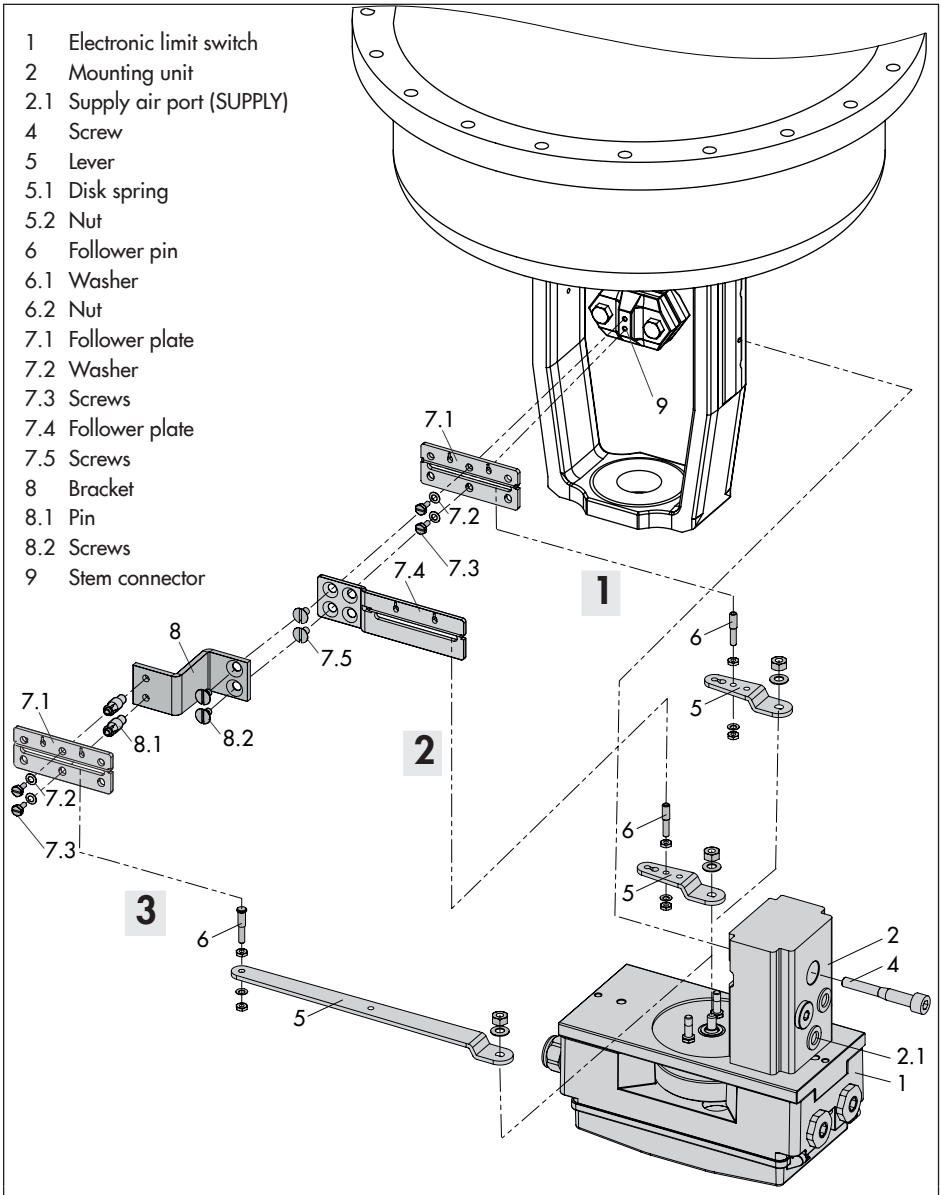


Fig. 7: *Mounting the electronic limit switch on linear actuators*

5.3 Attachment to rotary actuators

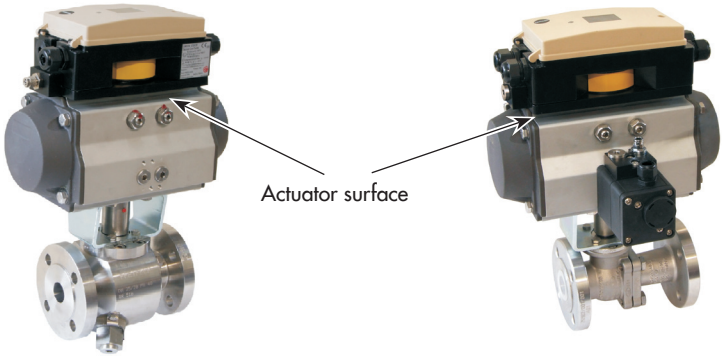
Fig. 8

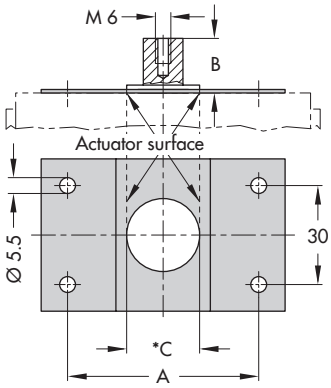
The electronic limit switch is mounted on rotary actuators according to VDI/VDE 3845, level 1 (2010). The version with integrated solenoid valve can be directly mounted to a Pfeiffer Type 31b Rotary Actuator.

Required accessories: see Table 1

Versions with integrated solenoid valve (Type 3738-20-xxx1400xxx000)

Version for external solenoid valve (Type 3738-20-xxx1000xxxx00)





Shaft height B	[mm]	20	30	50
Distance between holes A	[mm]	80	80/130	130

Fig. 8: *Mounting to rotary actuators according to VDI/VDE 3845, level 1 (2010)*

.1 Preparations

Version with integrated solenoid valve (Type 3738-20-xxx1400xxx000) (Fig. 10)

Two mounting platforms are available for the attachment (Fig. 9):

– Standard mounting platform for mounting onto Pfeiffer Type 31b Rotary Actuator with integrated air holes

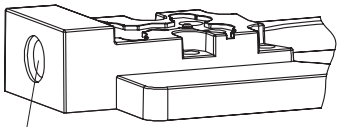
– Mounting platform for piping as required for mounting to standard actuators according to VDI/VDE 3845

The supply air is connected at the side of both mounting platforms. The blanking plug needs to be removed from the air connection.

1. Insert the molded seal (3) into the mounting platform (2) depending on the type of actuator (single-acting or double-acting).
2. Push the O-ring (3.1) onto the air duct of the molded seal (3).
3. Press the molded seal (4) onto the air ducts underneath the mounting platform (2).
4. **For attachment to rotary actuators with a 50 mm shaft height:**
   Press the second molded seal (4) onto the air ducts underneath **one** of the distance pieces (5).
5. Remove the blanking plug on the supply air port (SUPPLY) of the mounting platform (2).

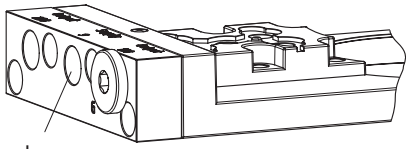
Version with external solenoid valve (Type 3738-20-xxx1000xxx00)

No preparation is necessary.



Supply pressure

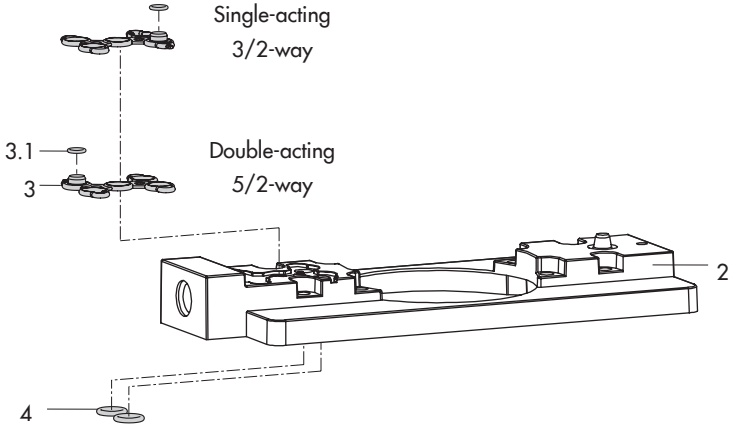
Standard mounting platform
(1380-1266 or 1380-1268)



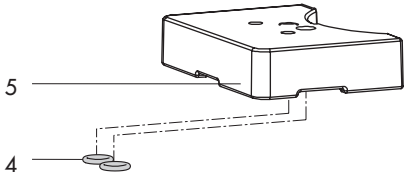
Supply pressure

Mounting platform with piping as required
(1380-1738 or 1380-1739)

Fig. 9: *Mounting platform*



Distance piece for attachment to rotary actuators with a 50 mm shaft height



1	Electronic limit switch
2	Mounting platform
3	Molded seal
3.1	O-ring
4	Molded seal
5	Distance piece

Fig. 10: *Preparations for mounting the electronic limit switch with integrated solenoid valve*

5.3.2 Attachment

The attachment depends on the shaft height of the rotary actuator upon which the electronic limit switch is to be mounted (Fig. 11).

Shaft height	20 mm	30 mm	50 mm
Screw with magnet (6)	SW 24, 30 mm	SW 24, 20 mm	SW 24, 20 mm
Fillister-head screws (10)	M5x16	M5x16	M5x40

1. **Attachment to rotary actuators with a 20 or 30 mm shaft height:** Place the spacers (11) on the inner holes of the actuator.
   Attachment to rotary actuators with a 50 mm shaft height: Place the distance pieces (5) on the rotary actuator.

Note concerning electronic limit switches with integrated solenoid valve:
Place the distance piece including inserted molded seal (4) over the air ducts of the actuator.

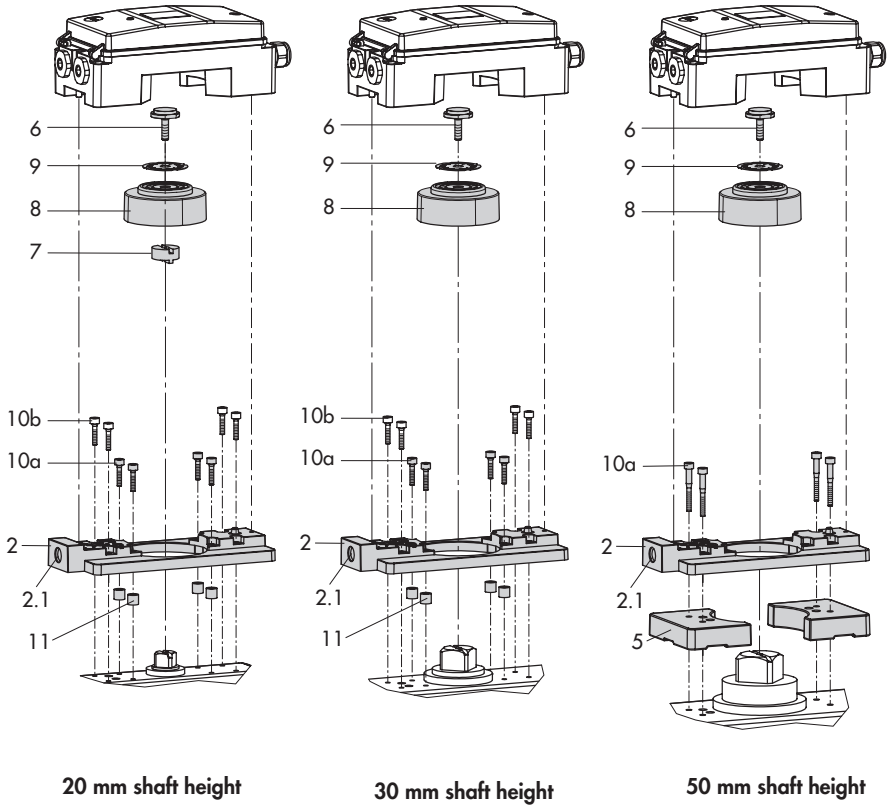
2. Fasten the mounting platform (2) on the rotary actuator:
   – **Version with integrated solenoid valve:** screws 10a and 10b
   – **Version for external solenoid valve:** screws 10a

Note concerning electronic limit switches with integrated solenoid valve:
Fasten the mounting platform (2), making sure that the air ducts located on the rotary actuator and the mounting platform are properly aligned.

3. **Attachment to rotary actuators with a 20 mm shaft height:** Place the adapter (7) and indicator wheel (8) one after the other onto the actuator shaft.
   Attachment to rotary actuators with a 30 or 50 mm shaft height: Place the indicator wheel (8) onto the actuator shaft.
4. Insert plate (9) into the indicator wheel (8).

NOTICE
Do not exceed the maximum torque of 8 Nm when fastening the screw with magnet (6).

5. Fasten the screw with magnet (6) onto the actuator shaft.
6. Bend the two flaps on the plate (9) towards the width flats of the screw with magnet (6).
7. Place the electronic limit switch on the mounting platform (2) as shown in Fig. 11 and fasten it using the two screws mounted on the device.
8. Electronic limit switch with integrated solenoid valve: connect supply air to supply air port (SUPPLY, 2.1).



1	Electronic limit switch	7	Adapter
2	Mounting platform	8	Indicator wheel
2.1	Supply air port (SUPPLY)	9	Plate
5	Distance piece	10	Fillister-head screws
6	Screw with magnet	11	Spacer

Fig. 11: *Mounting the electronic limit switch on rotary actuators*

6 Connections

WARNING!
Mount the electronic limit switch, keeping the following sequence:
- *Mount the electronic limit switch on the actuator. Refer to section 5.2 and 5.3.*
- *Connect the supply air. Refer to section 6.1 and 6.2.*
- *Connect the electrical power. Refer to section 6.3.*
- *Perform the start-up settings. Refer to section 8.*

The connection of the power may cause the actuator shaft to move, depending on the operating mode.

Do not touch the actuator shaft or obstruct it to avoid risk of injury to hands or fingers.

6.1 Pneumatic connections

NOTICE
Observe the following instructions to avoid damaging the electronic limit switch and/or solenoid valve:
- *Mount the pipes and screw fittings properly. Check them for leaks and damage at regular intervals and, if necessary, repair them. Before performing any repair work, depressurize any air lines to be opened.*
- *G ¼ or ¼ NPT threaded ports (depending on the device version) are used to connect the air pipes. Prevent water and dirt from entering the exhaust ports or vent plugs by installing a filter or by other suitable measures.*
- ***Operation with pressure reducing valves:** The K_{VS} coefficient of an upstream pressure reducing valve must be at least 1.6 times larger than that of the device.*
- ***Air pipe:** The minimum nominal size of the air pipe must be a pipe with an inside diameter of ≥ 4 mm. A larger nominal size must be used for connection lengths longer than 2 m.*
  Operation with external solenoid valve (Type 3738-20-xxx1000xxxx00):
  The input pressure must not exceed the maximum supply pressure of the external solenoid valve (refer to the specifications given by the solenoid valve manufacturer). Do not remove the blanking plug on the air port of the mounting platform (3)!
- *The supply air must be dry and free from oil and dust. The maintenance instructions for upstream pressure reducing stations must be observed.*
- *Blow through all air pipes and hoses thoroughly before connecting them.*

6.2 Supply pressure

Version with integrated solenoid valve (Type 3738-20-xxx1400xxx000)

Depending on the mounting platform used (ISO 228/1–G ¼ or ¼–18 NPT), customary fittings for metal or copper tubing or plastic hoses can be used.

The supply is connected at the side of the mounting unit or mounting platform.

Operation with external solenoid valve (Type 3738-20-xxx1000xxxx00)

Connect the supply air to the external solenoid valve following the instructions given by the solenoid valve manufacturer.

6.3 Electrical connection

DANGER!

Risk of electric shock and/or the formation of an explosive atmosphere!

For electrical installation, observe the relevant electrotechnical regulations and the accident prevention regulations that apply in the country of use.

The following regulations apply to installation in hazardous areas: EN 60079-14 (VDE 0165, Part 1) Explosive Atmospheres – Electrical Installations Design, Selection and Erection.

The maximum permissible values specified in the EC type examination certificate apply when connecting the intrinsically safe circuits.

Adhere to the terminal assignment specified in the certificate! Switching the assignment of the electrical terminals may cause the explosion protection to become ineffective.

Version: electronic limit switch with intrinsically safe external solenoid valve

The operating voltage and external solenoid valve are connected according to EN 60079-11, type of protection Ex i.

– ***Ex i terminals:*** *color: blue or black*

Version: electronic limit switch with non-intrinsically safe external solenoid valve

The operating voltage and external solenoid valve are connected according to EN 60079-7, type of protection Ex e.

The following applies to external connection:

– ***Ex i terminals:*** *color: blue*
– ***Ex e terminals:*** *color: black*
– ***Cable entry:*** *Ex e cable entry: black; Ex i cable entry: blue*

The cable entries of the electronic limit switch with external non-intrinsically safe solenoid valve must be certified according to type of protection Ex e according to ATEX.

The degree of protection (IP grade) of the cable entries and the blanking plug must be the same as that of the electronic limit switch.

Do not loosen enameled screws in or on the housing.

Note on the selection of cables and wires:

- *Observe **clause 11.2** for installation of the **non-intrinsically safe** circuits and **Clause 12 of EN 60079-14 (VDE 0165, Part 1)** for installation of the intrinsically safe circuits. Clause 12.2.2.7 of EN 60079-14 applies when running multi-core cables and wires with more than one intrinsically safe circuit.*
- *The radial thickness of the insulation of a conductor for common insulating materials (e.g. polyethylene) must not be smaller than 0.2 mm. The diameter of individual wires in a fine-stranded conductor must not be smaller than 0.1 mm. Protect the conductor ends against splicing, e.g. by using wire-end ferrules.*
- *When two separate cables are used for connection, an additional cable gland can be installed.*
- *Seal cable entries left unused with certified **Ex e** blanking plugs.*

The electronic limit switch is powered over the connection of the contact A according to IEC 60947-5-6. **An additional electrical power supply is not required.**

The function of the contacts A and B as well as the terminal labeling 41/42 or 51/52 depend on the direction of action:

	Connection		Position
	+	–	
PTO (power to open)			
Contact A	41	42	Fail-safe position (0 %)
Contact B	51	52	Operating position (100 %)
PTC (power to close)			
Contact A	51	52	Fail-safe position (100 %)
Contact B	41	42	Operating position (0 %)

Cable entry

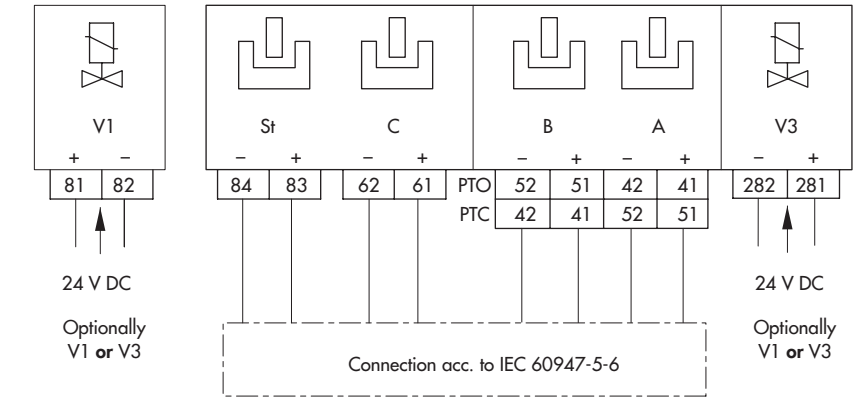
The threaded connection for the terminal compartment is designed with an M20 x 1.5 thread.

The screw terminals are designed for wire cross-sections of 0.2 to 1.5 mm². Tighten by at least 0.5 Nm.

! ***NOTICE***

*– The switching voltage of the integrated solenoid valve is connected either at the terminals V1 (81/82) **or** at the terminals V3 (281/282) (Type 3738-20-xxx1400xxx000).*

– Do not connect the switching voltage to the contacts A-St! Otherwise, the device will be damaged.



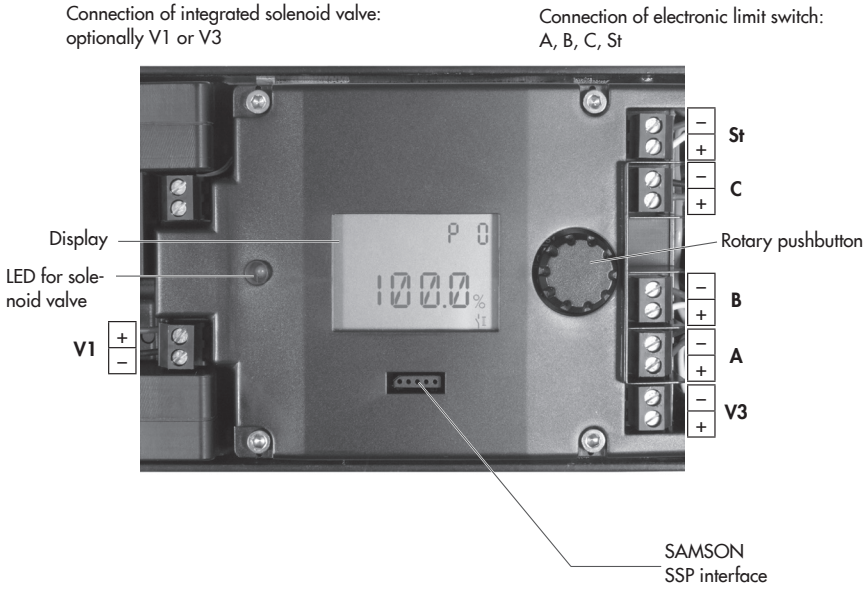
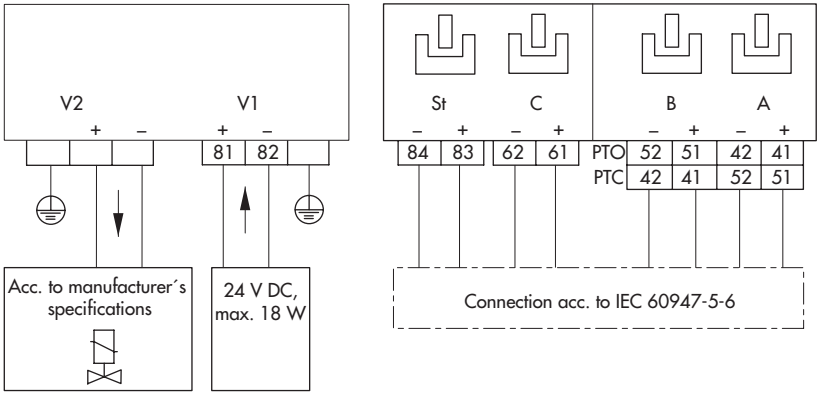


Fig. 12: *Electrical connection – Version for internal solenoid valve (Type 3738-20-xxx1400xxx000)*


V2
V1
+ – + –
81 82
Acc. to manufacturer´s specifications
24 V DC, max. 18 W
St C B A
– + – + – + – +
84 83 62 61
PTO 52 51 42 41
PTC 42 41 52 51
Connection acc. to IEC 60947-5-6

Connection of external solenoid valve: V1, V2

Connection of electronic limit switch: A, B, C, St

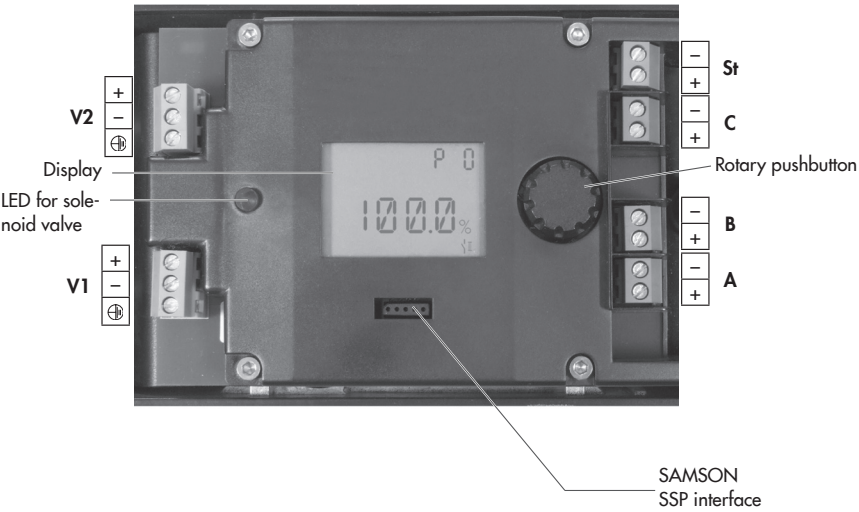


Fig. 13: *Electrical connection – Version for external solenoid valve (Type 3738-20-xxx1000xxxx00)*

7 Operator controls and readings

7.1 Rotary pushbutton

The rotary pushbutton (◎) is located underneath the housing cover.

The electronic limit switch is operated on site using the rotary pushbutton:

Turn ◎: Select parameters and values

Press ◎: Confirm setting/exit parameter

7.2 SAMSON SSP interface

The SAMSON SSP interface is located underneath the housing cover.

The local SAMSON SSP interface of the electronic limit switch needs to be connected over a serial interface adapter cable (see Table 1 on page 18) to the RS-232 or USB port of the computer before the TROVIS-VIEW software can be used.

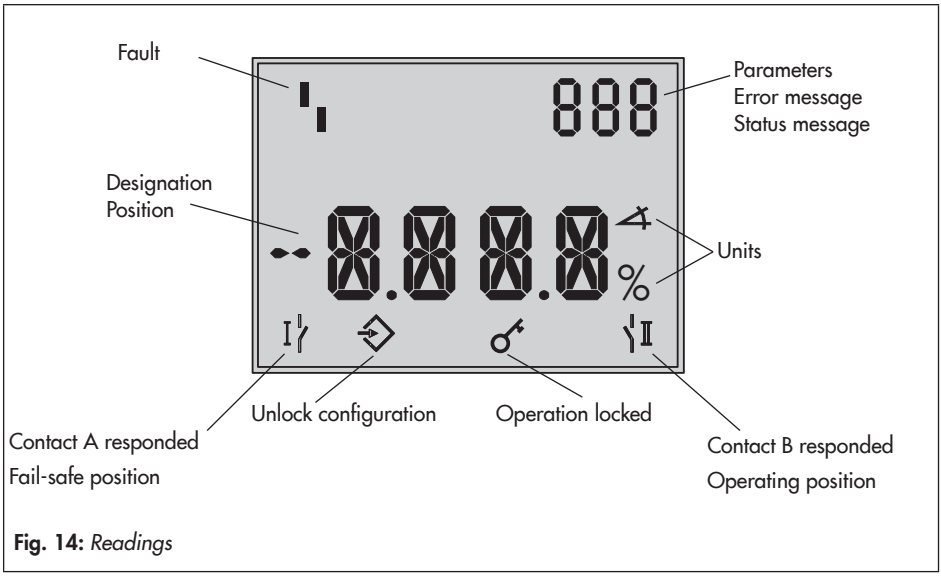


Fig. 14: *Readings*

7.3 Operating structure

The **P2** parameter allows the user to switch between the **RUN** operating mode and **SET** configuration mode. In the **SET** configuration mode, the parameters marked with an asterisk (*) (see section 13) can be changed and the device can be initialized.

To switch over modes, the key code must be entered first. The key code can be found on page 77. To avoid unauthorized use of the key code, remove the page or make the key code unreadable.

To meet the device design requirements to conform with SIL, the **SET** configuration mode is indicated by the fault alarm contact St responding after the device has been initialized successfully. In the display, the **SET** configuration mode is additionally indicated by the ⇨ icon. If the device has not yet been initialized or it has been reset to its default settings (P21), the three contacts A, B and C also respond.

After the device has been initialized and is in **RUN** operating mode, various states of the contacts can be set (see Table 3) depending on the control and status or error messages. Parameters cannot be changed or, for example, the device cannot be re-initialized in the **RUN** operating mode for reasons of safety.

Errors E0 to E8 have priority over the switching positions for reasons of safety. A serious device error E9 is additionally signalized by a wire breakage in accordance with IEC 60947-5-6.

Contact C can be used for monitoring the partial stroke test (PST). It responds when the valve position exceeds the selected limit ('PST step end' ± ½ 'PST tolerance band' (P14 ± ½ P15).

It is possible to monitor the PST target range when the P12 parameter (status readout for PST target range) is activated. In this case, the fault alarm contact St responds whenever the valve position is above or below the limit ('PST step end' ± ½ 'PST tolerance band'). This monitoring function is not active by default.

If the partial stroke test is not used, a third switching position can be indicated by contact C.

The contacts can indicate the operating states listed in Table 3.

The operating structure is shown on the following pages in the form of schematic diagrams:

– Placing the electronic limit switch into operation using its default settings (page 36)
– Changing the operating mode and parameter settings (page 37)

Table 3: *Indication of operating states*

Contacts A, B, C can configured as required (NC or NO contact) Contact St is always a NC contact				
A	**B**	**C**	**St**	
Possible operating states in SET configuration mode				
⦿	⦿	⦿	⦿	Device not initialized/default settings
⦿	O	⦿	⦿	Device initialized, fail-safe position
O	⦿	O	⦿	Device initialized, operating position
Possible operating states in RUN operating mode				
⦿	O	⦿	O	Fail-safe position
O	⦿	O	O	Operating position
⦿	O	⦿	⦿	Fail-safe position, F0 to F10 status messages or E10 error message
O	⦿	O	⦿	Operating position, F0 to F10 status messages or E10 error message
⦿	⦿	⦿	⦿	E0 to E8 error messages, F10 status message
⦿	⊗	⦿	⦿	Error E9 (serious device error)
Possible operating states during partial stroke test (PST), refer to section 9.2 for further details				
O	O	O	O	PST started, PST target range not reached yet
O	⦿	⦿[1)]	O	PST target range reached/PST completed successfully
O	⦿	O	O	PST not completed successfully, P12 = NO
O	⦿	O	⦿	PST not completed successfully, P12 = YES

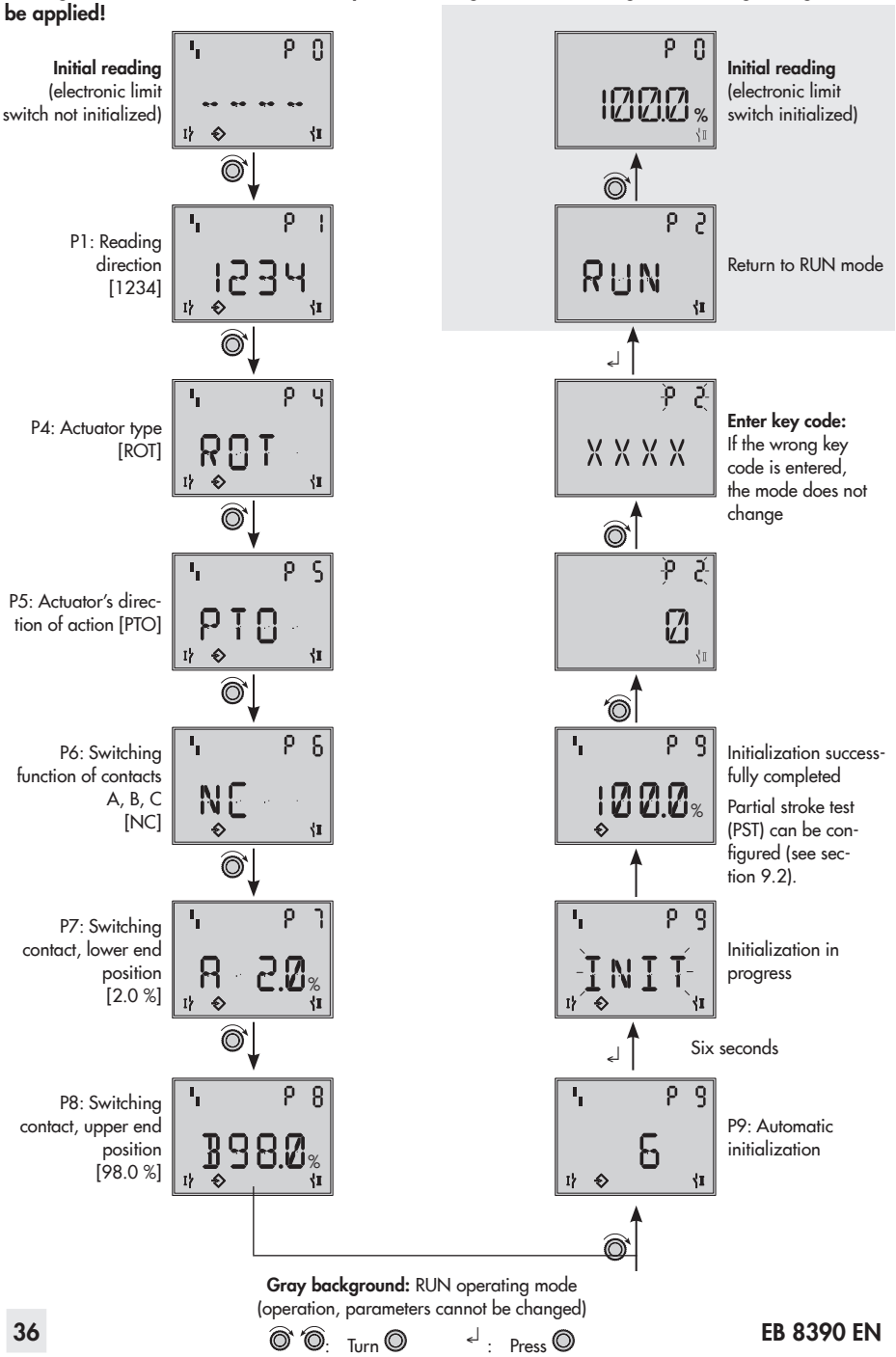
1) The contact remains activated three seconds after the valve moves out again of the PST target range.

O NC = closed; NO = open

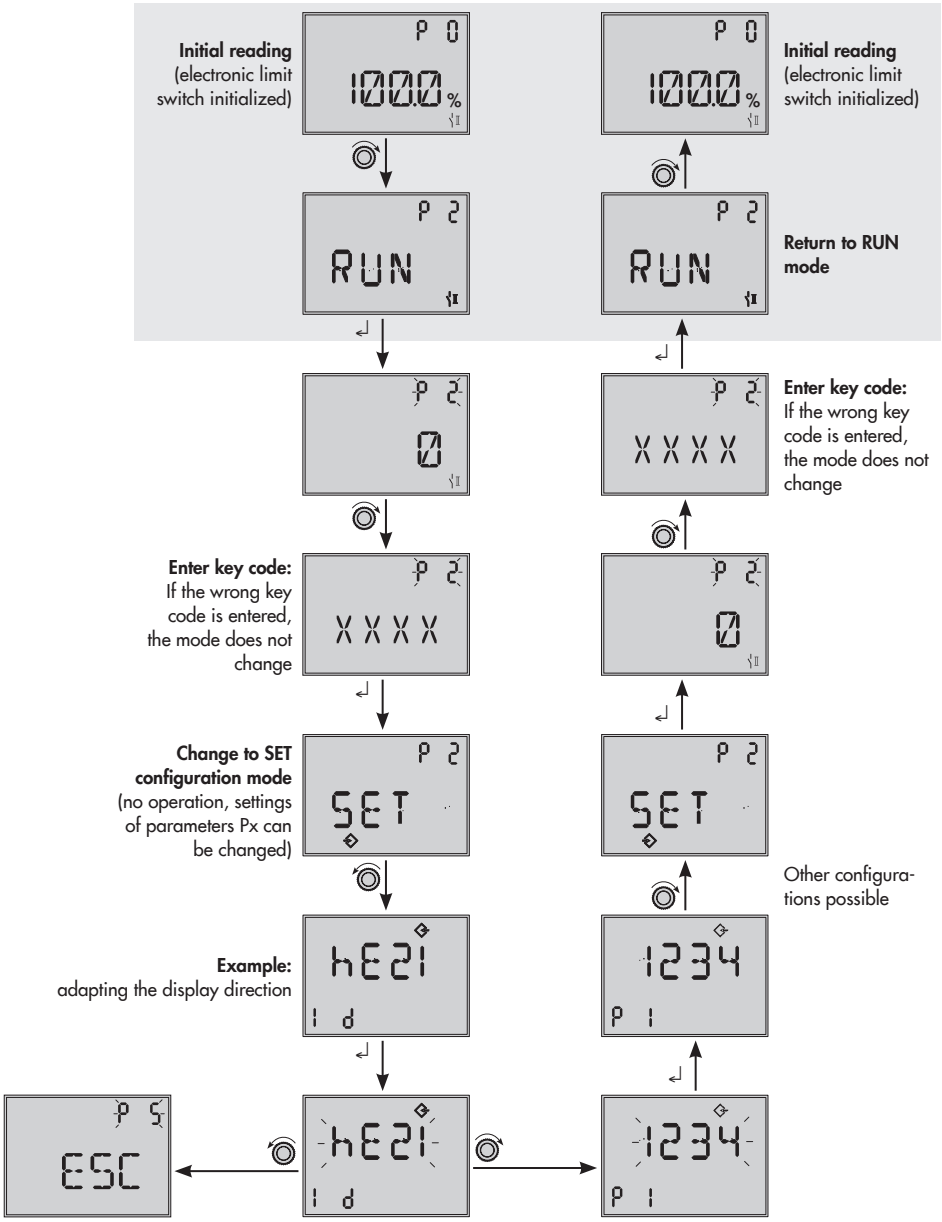
⦿ NO = open; NC = closed

⊗ Wire break

Placing the electronic limit switch into operation using its default settings – Switching voltage must be applied!


Initial reading (electronic limit switch not initialized)
P1: Reading direction [1234]
P4: Actuator type [ROT]
P5: Actuator's direction of action [PTO]
P6: Switching function of contacts A, B, C [NC]
P7: Switching contact, lower end position [2.0 %]
P8: Switching contact, upper end position [98.0 %]
Initial reading (electronic limit switch initialized)
Return to RUN mode
Enter key code: If the wrong key code is entered, the mode does not change
Initialization successfully completed
Partial stroke test (PST) can be configured (see section 9.2).
Initialization in progress
Six seconds
P9: Automatic initialization
Gray background: RUN operating mode (operation, parameters cannot be changed)
: Turn
: Press

Changing the operating mode and parameter settings



Gray background: RUN operating mode (operation, parameters cannot be changed)

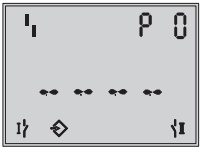
: Turn : Press

8 Start-up

WARNING!
Mount the electronic limit switch, keeping the following sequence:
– *Mount the electronic limit switch on the actuator. Refer to section 5.2 and 5.3.*
– *Connect the supply air. Refer to section 6.1 and 6.2.*
– *Connect the electrical power. Refer to section 6.3.*
– *Perform the start-up settings. Refer to section 8.*

NOTICE
Perform the start-up settings in the same sequence as described (section 8.1 to 8.7).

Reading after connecting the electrical power supply:



P0: Display when the electronic limit switch has not yet been initialized

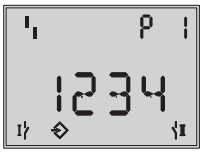
– The fault alarm icon and – – – – appear on the display when **the electronic limit switch has not yet been initialized**. The electronic limit switch is not in service. Parameter settings can be changed (P2 = SET). Refer to page 37.

Note:
The current angle of rotation is set to 0° by pressing the rotary pushbutton (◎).

– The current angle of rotation is displayed in % when the electronic limit switch has been initialized. To change parameter settings, the configuration mode (SET) must be activated. See page 37.

8.1 Adapting the display direction

The reading on the electronic limit switch display can be turned by 180° to adapt it to how the electronic limit switch is mounted.



P1: Reading direction

If the displayed data appear upside down, proceed as follows:

Turn ◎ → **P1**

Press ◎, **P1** blinks

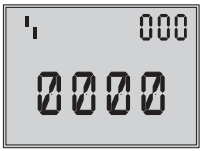
Turn ◎ 1234/ 4321

Press ◎ to confirm reading direction and to exit the parameter.

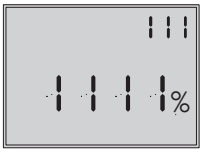
8.2 Verifying readings on display

NOTICE
For safety-instrumented systems, the display's functioning must be tested.

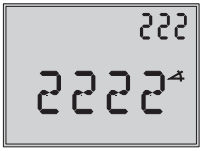
The display's functioning is checked using the **P3** parameter.



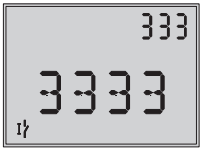
P3: Display reading 1



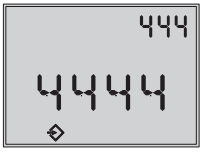
P3: Display reading 2



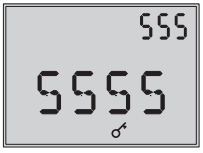
P3: Display reading 3



P3: Display reading 4

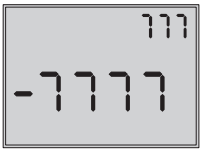


P3: Display reading 5



P3: Display reading 6

P3: Display reading 7



P3: Display reading 8

P3: Display reading 9

P3: Display reading 10

Turn ◎ → **P3**

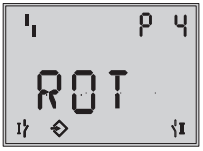
Press ◎, reading 1

Turn ◎, reading 2 to 10

Press ◎ to confirm testing. The last test of the display readings is saved with a time stamp in the electronic limit switch. The time stamp can be read in TROVIS-VIEW.

8.3 Determining the actuator type

The setting of the actuator type (rotary or linear actuator) is made using **P4** parameter.



P4: Actuator type
Default: ROT

Turn ◎ → **P4**

Press ◎, **P4** blinks

Turn ◎ → ROT (rotary actuator)/
LIN (linear actuator)

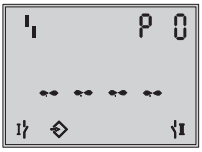
Press ◎ to confirm the actuator type and to exit the parameter.

Note:
*After initialization, this parameter is locked and can first be selected and changed after performing a reset to default settings (**P21**).*

8.4 Determining the direction of action

Observe the assignment of contacts A and B depending on the direction of action (page 79)!

The setting is made using **P5** parameter.



P5: Direction of action
Default: PTO

Turn ◎ → **P5**

Press ◎, **P5** blinks

Press ◎ → **PTC** (power to close)/
PTO (power to open)

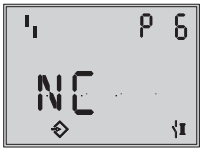
Press ◎ to confirm direction of action and to exit the parameter.

Note:
*After initialization, this parameter is locked and can first be selected and changed after performing a reset to default settings (**P21**).*

8.5 Determining the switching function of contacts

The setting is made using **P6** parameter.

Note:
The local operation allows the contacts A, B and C to be defined together as NO or NC contacts. The contacts can be configured separately in TROVIS-VIEW.



P6: Switching function of contacts A, B and C
Default: NC

Turn ◎ → **P6**

Press ◎, **P6** blinks

Turn ◎ → **NO/NC**

Press ◎ to confirm switching function and to exit the parameter.

8.6 Adjusting the limit contacts

A limit signal is issued by the limit switches for fail-safe position (contact A) and for operating position (contact B). The contacts A and B can be adjusted within the range.

The switching response of the contacts can be adjusted within the actuator's travel range.

The switching responses of the contacts are set in the **P7** (lower end position) and **P8** (upper end position) parameters.

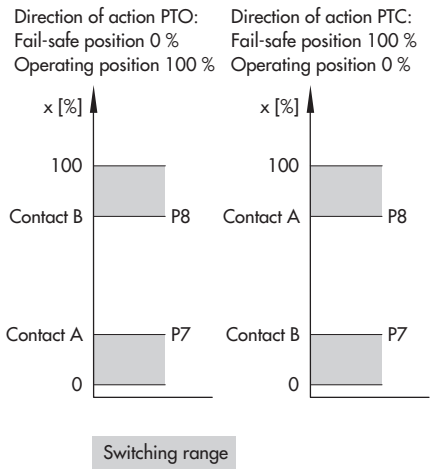
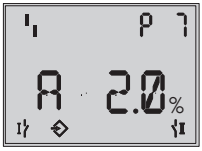


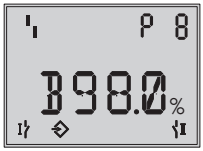
Fig. 15: *Switching range of end positions*

Note:
*The following correlations apply to the setting ranges of the switching ranges for lower end position (**P7**) and the upper end position (**P8**):*
*– **P7**: 0.5 % to (P8 – 2.0 %)*
*– **P8**: (P7 + 2.0 %) to 99.5 %*

Observe the assignment of contacts A and B depending on the direction of action (page 79)!



P7: Switching contact, lower end position
Default: 2.0 %
Example: Fail-safe position for PTO



P8: Switching contact, upper end position
Default: 98.0 %
Example: Operating position for PTO

Turn ◎ → **P7/P8**
Press ◎, **P7/P8** blinks
Turn ◎ → Required switching value
Press ◎ to confirm the switching value and to exit the parameter.

8.7 Initialization

WARNING!
– The initialization must only be started when the switching voltage is connected and the actuator is in the operating position.
– Check the max. permissible signal pressure before starting initialization.
– The actuator is moved through its entire travel range during initialization. Therefore, do not start initialization while a process is running, but only during start-up, when all shut-off valves are closed.

NOTICE
*After the electronic limit switch has been mounted onto another actuator or its mounting location has been changed and prior to re-initializing, the electronic limit switch needs to be reset to its default setting (Code **P21**). Refer to section 8.10 on page 45).*

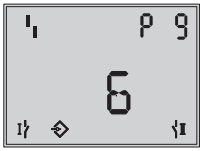
Note:
If an electronic limit switch is replaced with another electronic limit switch of the same type, the replaced electronic limit switch may not need to be re-initialized, provided certain conditions are met. Refer to section 8.8 Replacing an electronic limit switch on page 44.

After the electronic limit switch has been initialized, the current valve position appears in % on selecting **P0**. Keep the rotary pushbutton (◎) pressed to display the reading as an angle (°).

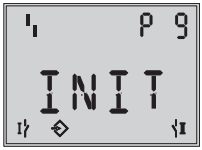
Two types of initialization are available:
– Automatic initialization with **P9** parameter
– Manual initialization with **P10** parameter by manually confirming the end positions (POS1 and POS2)

8.7.1 Start automatic initialization

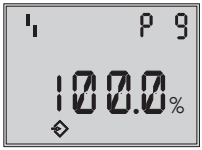
Note:
The automatic initialization can be canceled by pressing the rotary pushbutton (◎). ESC appears on the display.
Data saved in the electronic limit switch prior to the initialization can be restored by pressing the rotary pushbutton (◎) again.



P9: Initialization is being prepared



P9: Initialization in progress



P9: Initialization successfully completed

Turn ◎ → **P9**

Press ◎ six seconds long. The seconds remaining until the initialization starts appear on the display.

Initialization starts (display: INIT): The valve moves twice from the operating position to the fail-safe position and back again to the operating position. It measures the travel between the end stops as well as the dead time and transit times for opening and closing the valve.

After the initialization has been successfully completed, the current valve position in % is indicated.

The electronic limit switch is in the configuration mode (SET).

To start operation, exit the configuration mode. See page 37.

The automatic initialization is automatically canceled if a fault occurs (ERR on the display). The initialization error can be read in the ERR parameter level:

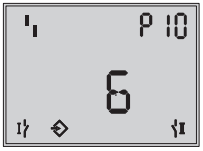
- **E0**: No initialization
- **E1**: Actuator does not move
- **E2**: Min. travel not reached
- **E3**: Max. travel exceeded
- **E4**: Actuator travels too fast
- **E5**: No switching voltage applied
- **E6**: Time-out

8.7.2 Start manual initialization

Note:

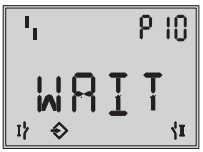
– Select ESC on the display and press the rotary pushbutton to cancel the manual initialization. Data saved in the electronic limit switch prior to the initialization can be restored by pressing the rotary pushbutton (◎) again.

– If the electronic limit switch was initialized manually, the partial stroke test cannot be started (refer to section 9.2 on page 46).

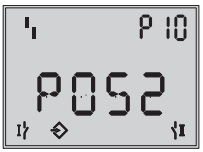


P10: Initialization is being prepared

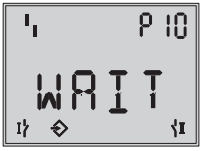
P10: Confirmation of fail-safe position (solenoid valve de-energized)



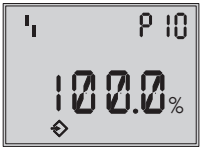
P10: Fail-safe position found



P10: Confirmation of operating position (solenoid valve energized)



P10: Operating position found



P10: Initialization successfully completed

Turn ◎ → **P10**

Press ◎ six seconds long. The seconds remaining until the position check starts appear on the display.

Display: **POS1**

☞ Move the valve to the fail-safe position manually (de-energize the solenoid valve).

Press ◎ to confirm the fail-safe position → **WAIT**

The electronic limit switch saves the fail-safe position.

Display: **POS2**

☞ Move the valve to the operating position manually (energize the solenoid valve).

Press ◎ to confirm the operating position → **WAIT**

The electronic limit switch saves the operating position.

After the initialization has been successfully completed, the current valve position in % is indicated.

The electronic limit switch must be in the configuration mode (SET).

To start operation, exit the configuration mode. See page 37.

The manual initialization is automatically canceled if a fault occurs (ERR on the display).
The initialization error can be read in the ERR parameter level:

– **E0**: No initialization
– **E2**: Min. travel not reached
– **E3**: Max. travel exceeded
– **E6**: Time-out

8.8 Replacing an electronic limit switch

An (old) electronic limit switch can be replaced by another (new) electronic limit switch of the same type by performing an end position calibration in the operating or fail-safe position, but without having to initialize the new one, provided the following conditions are met:

– **Data from the electronic limit switch being replaced are downloaded and saved in TROVIS-VIEW.**
– **The screw with magnet must not be unfastened while the electronic limit switch is being replaced.**
– **The end stops of the valve must not be changed while the electronic limit switch is being replaced.**

Replacing an electronic limit switch

☞ Download and save data from the electronic limit switch being replaced in TROVIS-VIEW.
☞ Replace electronic limit switch.
☞ Load data from TROVIS-VIEW onto the new electronic limit switch.
☞ Perform an end position calibration as described in section 8.9.

8.9 Zero/end position calibration

When the zero point or end positions are incorrect, it may be necessary to recalibrate them. Always perform an end position calibration for the fail-safe position and for the operating position.

The electronic limit switch must be in the configuration mode (SET). See page 37.

P11: Zero/end position calibration in progress

Turn ◎ → **P11**

Press ◎ six seconds long. The seconds remaining until the end position calibration starts appear on the display.

The current valve position is set to the end stop (0 % or 100 %).

The electronic limit switch must be in the configuration mode (SET).

To start operation, exit the configuration mode. See page 37.

The end position calibration is automatically canceled if a fault occurs (ERR on the display).

The error can be read in the ERR parameter level:

– **E6**: Time-out
– **E8**: Unable to calibrate end positions

8.10 Reset to default settings

This function resets all parameters to the factory default settings (see parameter list in section 13 on page 57). All error and status messages are also reset.

> ***NOTICE***
> *After performing a reset, the electronic limit switch needs to be re-initialized (see section 8.7).*

The electronic limit switch must be in the configuration mode (SET). See page 37.

P21: Reset

Turn ◎ → **P21**

Press ◎, **P21** blinks

Turn ◎ → **RST**

Press ◎.
The initialization values are reset to the default settings.

☞ Re-initialize the electronic limit switch (see section 8.7).

☞ Set PST parameters (see section 9.2).

9 Operation

WARNING!
The actuator shaft moves while the electronic limit switch is operating.
Do not touch the actuator shaft or obstruct it to avoid risk of injury to hands or fingers.

9.1 Lock operation

When the locking function is active, the electronic limit switch can only be operated remotely using the TROVIS-VIEW software. The locked local operation of the electronic limit switch is indicated on the display by the ⚷ icon.

The local operation is locked and unlocked in the TROVIS-VIEW software.

9.2 Partial stroke test (PST)

WARNING!
Ear protection must be worn if the test is performed on the version with integrated solenoid valve while the housing cover is open!

The probability of failure on demand (PFD) can be reduced and maintenance intervals can be extended by the partial stroke test (PST).
This helps prevent the valve from seizing up in its operating position.

The following conditions must be met before the partial stroke test (PST) can be performed:

– An automatic initialization must have been performed. Refer to section 8.7.1.
– The switching voltage must be applied.

Test procedure (Fig. 16)

The electronic limit switch issues pulses of various lengths to the solenoid valve (briefly de-energizing it) during the partial stroke test (PST), moving the valve further towards the fail-safe position.

The test has been completed successfully when the valve has reached the target range ('PST step end' ± ½ 'PST tolerance band') by one pulse, but not exceeded it. When the target range is reached, contact C responds

The analysis of a successfully completed test provides the following data:

– PST pulse length
– PST dead time
– PST transit time SV de-energized
– PST hold time
– PST transit time SV energized
– PST travel
– PST status

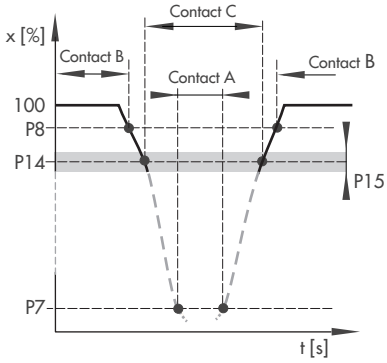
If the test could not be completed, the corresponding F8 or F9 status message is generated:

– **F8**: No switching voltage during PST
– **F9**: Time-out during PST

Note:

– *If the travel of the PST is monitored and, if necessary, the status messages F6 ('Min. value for PST not reached') and F7 ('Max. value for PST exceeded') are to be generated, the* **P12** *parameter must be set to YES.*

– *Contact C can be used to indicate a third switching position. Refer to following example for direction of action PTO.*



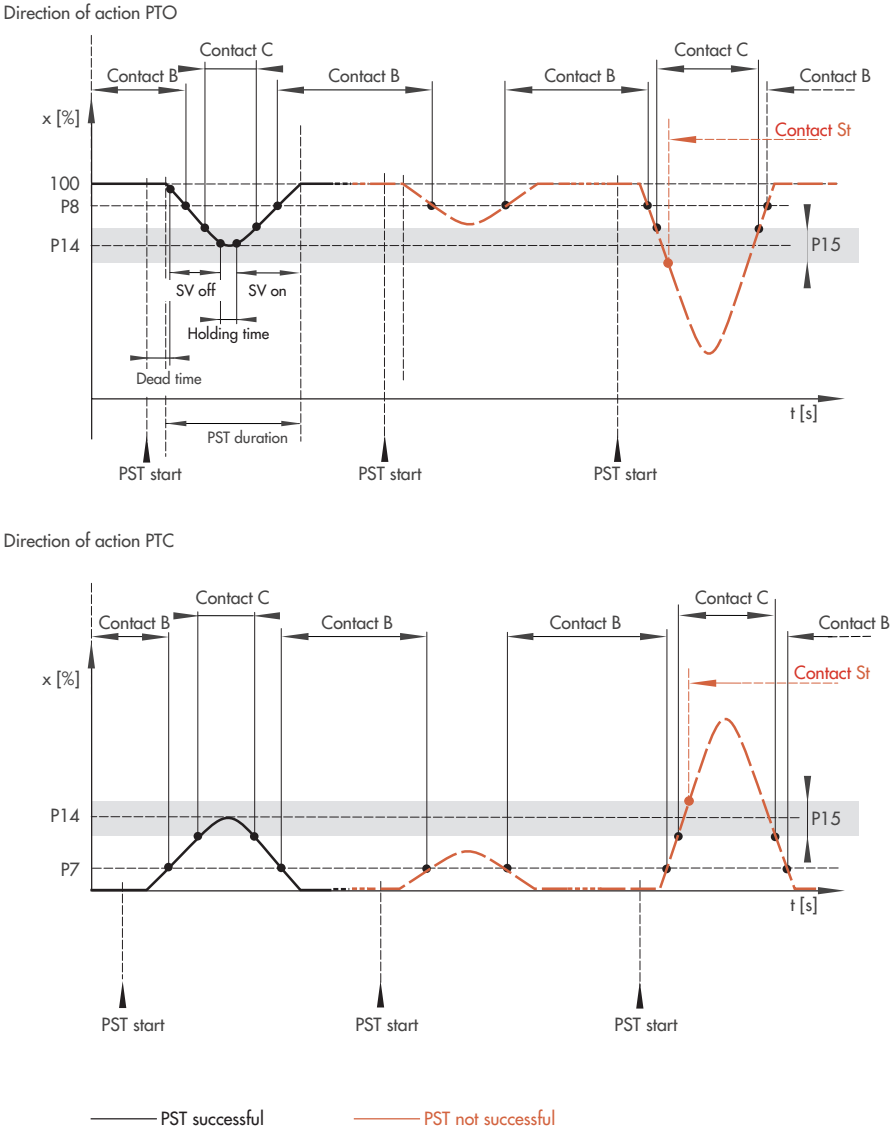


Fig. 16: *Partial stroke test (PST)*

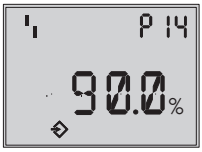
9.2.1 Defining the PST target range

Define the target range by configuring **P14** and **P15** parameters.

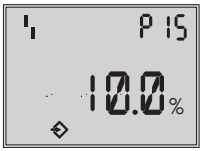
PST target range = 'PST step end' (P14) ± ½ 'PST tolerance band' (P15)

> ***NOTICE***
> *It is important to take the process conditions (e.g. pressure, medium, dead time, breakaway torque and torque of the valve) into account on defining the PST target range. A valve that opens (PTC) and closes (PTO) too far may affect the process!*

The electronic limit switch must be in the configuration mode (SET). See page 37.



P14: PST step end
Default: 90.0 %



P15: PST tolerance band
Default: 10.0 %

Turn ◎ → **P14/P15**

Press ◎, **P14/P15** blinks

Turn ◎ → PST step end/PST tolerance band

Press ◎ to confirm the value and to exit the parameter.

9.2.2 Starting the partial stroke test

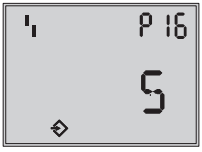
A single PST test can be started manually or a regular PST test can be started automatically at defined time intervals.

Start PST automatically at defined intervals (RUN mode)

The test is performed automatically after a time interval (days) entered in **P16** ('Automatic PST).

> ***NOTICE***
> *The automatic test causes the valve to leave its operating position without a switching demand.*

> ***Note:***
> *The default setting **OFF** causes the automatic test to be deactivated.*



P16: Start automatic PST

Turn ◎ → **P16**

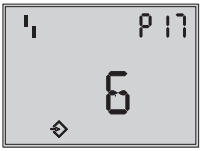
Press ◎, **P16** blinks

Turn ◎ → Required time period [days]

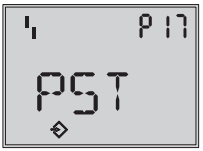
Press ◎ to confirm the entry and to exit the parameter.

Start PST manually (SET or RUN configuration mode)

A single test is started by the **P17** parameter.



P17: Start of PST is being prepared



P17: Test in progress

Turn ◎ → **P17** (travel range in %)

Press ◎ six seconds long.
The seconds remaining until the test starts appear on the display.

The test starts (display: PST).

Note:
A test in progress can be canceled by pressing the rotary pushbutton (◎). ESC appears on the display.

9.2.3 Configuration example based on PTO direction of action

The valve is normally open (operating position = 100 %). In the event of emergency, the valve is to close (fail-safe position = 0 %). The actuator's direction of action is therefore PTO (power to open), configured in the P5 parameter.

The upper end position (P8) is set at 98 %. This value is the same as the default setting. Contact B is activated when the valve moves beyond this value.

To prevent the valve seizing in the open position, a partial stroke test is to be performed on a weekly basis. During the partial stroke test, the valve is moved from the operating position towards the fail-safe position to a step end of 90 % by briefly de-energizing the solenoid valve. During the test, the valve must not move beyond a position of 85 % and a status message is activated for monitoring purposes if the PST target range is not reached or exceeded.

The following settings are made to the initialized electronic limit switch in the example while taking the process conditions into consideration:

1. **Select configuration mode SET (P2)**

   The parameters required to configure the partial stroke test can only be set in the SET configuration mode (P2 = SET).

2. **Define PST target range (P14, P15)**

   The PST target range is made up of the 'PST step end' (P14) and the 'PST tolerance band' (P15).

   P14 ('PST step end') = 90 %

   P15 ('PST tolerance band') = 10 %

   → PST target range = 90 % ± 5 %
   = 85 % … 95 %

3. **Activate the monitoring of the PST target range (P12)**

   The monitoring of the target range as well as the status readout F6 'Min. value for PST not reached' and F7 'Max. value for PST exceeded' are activated by the P12 parameter = YES.

When the status message F6 or F7 is generated, check the attachment, supply air lines and the valve. If necessary, the settings of the target range must be changed accordingly (P14 and P15). See "Define PST target range (P14, P15)" in point 2.

4. **Start automatic PST (P16)**

   P16 = 7 days

   The test starts automatically once a week after switching to RUN operating mode. **The valve leaves the operating position (100 %) without a switching demand.**

5. **Select RUN operating mode (P2)**

   The countdown starts after the electronic limit switch has been switched to the RUN operating mode (P2 = RUN).

6. **Evaluate PST (Fig. 17)**

   A partial stroke test is successfully completed when the valve reaches the defined PST target range, but has not moved beyond it. Contact C responds when the valve enters the PST target range and remains activated three seconds after the valve leaves the PST target range again.

   The status contact St remains in the no response state (> 2.1 mA) as long as the PST target range is reached and not exceeded. If the status contact St is activated by the valve not reaching the PST target range, it remains activated until the next partial stroke test is started. This partial stroke test is then reevaluated.

   The evaluation of the performed test provides the following data:

   – PST pulse length
   – PST dead time
   – PST transit time SV de-energized
   – PST hold time
   – PST transit time SV energized
   – PST travel
   – PST status

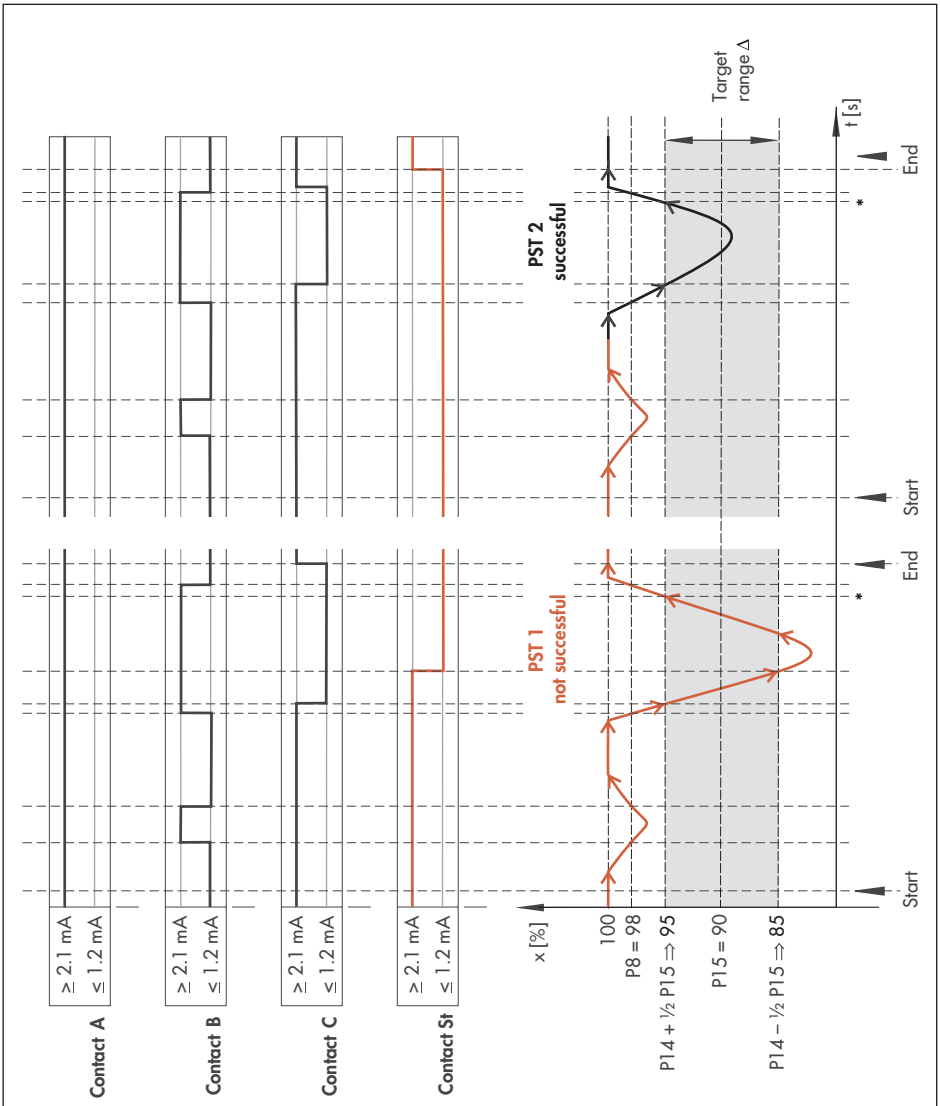
   Check the voltage supply and solenoid valve wiring when the status message F8 ('No switching voltage during PST') is generated.

   Check the attachment and supply air line when the status message F9 ('Timeout during PST') is generated.

   The last 10 evaluations are saved in a non-volatile memory in the electronic limit switch and can be read in the TROVIS-VIEW software.

   The solenoid valve is briefly de-energized by pulses issued by the electronic limit switch to close the valve.

In this example, the valve does not reach the PST target range during the first partial stroke test and moves beyond it. The test was not successfully completed. In the second automatic test, the valve initially does not reach the PST target range. The next step though ends in the PST target range, meaning the test has been successfully completed.



* The contact C remains activated 3 seconds after the valve moves out again of the PST target range.

Fig. 17: *Example: Course of first two partial stroke tests*
The graph shows the states when A, B and C contact setting = NC (P6)

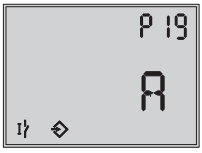
9.3 Testing the contacts

The following contacts can be tested in the **P19** parameter.

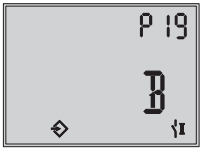
- **Contact A**: Limit switch for fail-safe position
- **Contact B**: Limit switch for operating position and simulation of wire break (B_LB parameter appears on the display to meet requirements of IEC 60947-5-6)
- **Contact C**: Indicates that the target range has been reached during the partial stroke test or that an intermediate position has been reached. See section 9.2**.**
- **Contact St**: Fault alarm contact

The electronic limit switch must be in the configuration mode (SET). See page 37.

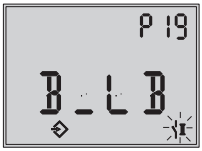
Display when P6 = NC



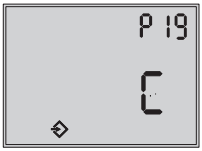
P19: Simulation of contact A
(limit switch for fail-safe position)



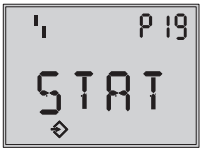
P19: Simulation of contact B
(limit switch for operating position)



P19: Simulation of wire break at contact B



P19: Simulation of contact C:
(signal on reaching target range during partial stroke test)



P19: Simulation of fault alarm contact

Turn ◎ → **P19**

Press ◎, **P19** blinks

Turn ◎ → **A/B/B_LB/C/St**
All contacts are activated.

Press ◎.
The contact selected is deactivated while the rotary pushbutton is pressed.

Turn ◎ → ESC

Press ◎ to exit the parameter setting.

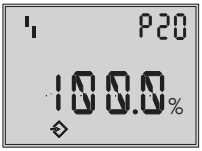
Note:
When P6 = NO, the logic for contacts A, B and C is reversed. B_LB on the display means the contact C is activated.

9.4 Testing the solenoid valve

You can de-energize the solenoid valve while the voltage is still applied using the **P20** parameter. In this case, the valve moves to the fail-safe position.

Observe the assignment of contacts A and B depending on the direction of action (page page 79)!

The electronic limit switch must be in the configuration mode (SET). See page 37.



P20: Testing solenoid valve

Example: PTO

Turn ◎ → **P20**

Press ◎, **P20** blinks and **ESC** appears on the display.

Turn ◎ → Operating position

Turn ◎ to de-energize the solenoid valve (the valve moves to the fail-safe position) while the rotary pushbutton is pressed.

Turn ◎ → ESC

Press ◎ to exit the parameter.

9.5 Faults

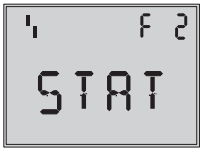
9.5.1 Status messages

When a status message is generated, the ⚠ fault icon appears on the display in the RUN operating mode. In addition, the fault alarm contact St is activated.

The possible cause of the fault is indicated by the **STAT** parameter reading under **F0** to **F10**.

Note:

- *The status message* **F4** *('Actuator transit time exceeded') is only generated when a fault occurs and when* ***P13*** *≠ OFF.*
- *The status messages* ***F6*** *('Min. value for PST not reached') and* ***F7*** *('Max. value for PST exceeded') are only generated when a fault occurs and when* ***P12*** *= YES.*
- *The status message* ***F10*** *indicates that one of the error messages* ***E0*** *to* ***E10*** *has been generated.*



Example:

F2: Limit of maximum rotary motion (P26) exceeded

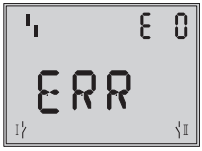
Refer to the parameter list (section 13.1 on page 61) for possible causes and the recommended action.

9.5.2 Error messages

When an error message is generated, the ⚠ fault icon appears on the display in the **RUN** operating mode.

The possible cause of the fault is indicated by the **ERR** parameter reading under **E0** to **E10**.

If an error **E0** to **E8** exists, all contacts (A, B, C and St) respond for reasons of safety.
Error **E9** (device error 1) causes a wire break (contact B) to be additionally signaled to meet requirements of IEC 60947-5-6.
Error **E10** (device error 2) causes the switching position to be displayed unchanged.



Example:

E0: No initialization

Refer to the parameter list (section 13.1 on page 61 and section 13.2 on page 63)

for possible causes and the recommended action.

9.5.3 Confirming status and error messages

Note:
*The status messages **F0**, **F1**, **F3** and **F10** as well as the error message **E0** cannot be confirmed.*

The electronic limit switch must be in the configuration mode (SET). See page 37.

Turn ◎ → **F0**/…/**F10**, **STAT** or **E0**/…/**E10**, **ERR**

Press ◎, **F0**/…/**F10**, **E1**/…/**E10** blinks

Turn ◎ → **RST**

Press ◎ to confirm status/error message.

10 Maintenance, calibration and work on equipment

Interconnection with intrinsically safe circuits to check or calibrate the equipment inside or outside hazardous areas is to be performed only with intrinsically safe current/voltage calibrators and measuring instruments to rule out any damage to components relevant to explosion protection.

Observe the maximum permissible values specified in the certificates for intrinsically safe circuits.

10.1 Maintenance

The electronic limit switch does not require any maintenance when used for its intended purpose.

DANGER!
Risk of electrostatic charging!
Due to the high surface resistance of the enclosure cover ($R_{Isol.} \geq 10^9\ \Omega$), installation and maintenance on the equipment must be performed in such a way that electrostatic charging cannot occur.

Version with integrated solenoid valve (Type 3738-20-xxx1400xxx000)

There are filters with a 100 µm mesh size in the pneumatic connections for supply and output which can be removed and cleaned, if required.

The maintenance instructions of any upstream supply air pressure reducing stations must be observed.

11 Servicing explosion-protected devices

If a part of the device on which the explosion protection is based needs to be serviced, the device must not be put back into operation until a qualified inspector has assessed it according to explosion protection requirements, has issued an inspection certificate or given the device a mark of conformity.

Inspection by a qualified inspector is not required if the manufacturer performs a routine test on the device prior to putting it back into operation. Document the passing of the routine test by attaching a mark of conformity to the device.

Replace explosion-protected components only by original, routine-tested components provided by the manufacturer.

Devices that have already been used outside hazardous areas and are intended for future use inside hazardous areas must comply with the safety requirements placed on serviced devices. Before being operated inside hazardous areas, test the devices according to the specifications for servicing explosion-protected devices.

12 Firmware update (serial interface)

Firmware updates on electronic limit switches currently in operation can be performed as follows:

When updates are performed by a service employee appointed by SAMSON, the update is confirmed on the electronic limit switch by the test mark assigned by SAMSON's Quality Assurance.

In all other cases, only plant operator personnel with written approval may perform updates. Updates are to be confirmed by approved personnel on the device.

Laptops and PCs connected to the power supply must not be used without an additional protective circuit.

This does not apply to laptops in battery operation. In this case, it is assumed that a battery-powered laptop runs briefly for software programming or testing purposes.

a) **Updates outside the hazardous area:**

   Remove the electronic limit switch from the plant and update it outside the hazardous area.

b) **Updates on site:**

   Updates on site are only permitted after the plant operator presented a signed hot work permit.

   After updating has been completed, add the current firmware to the nameplate; this can be done using labels.

13 Parameter list

No.	Parameter – Readings, values [default setting]	Description	
Parameters marked with an asterisk (*) can only be changed when the electronic limit switch is in the SET configuration mode (set in **P2**).			
P0	Info: actual value	**After initialization:** current valve position in % Keep ◎ pressed down –> current valve position in ° (angle) **Prior to initialization:** Travel in °	See section 8
P1	Reading direction 1234 · ⇂23Ɐ · ESC	The reading direction of the display is turned by 180°.	See section 8.1
Start-up			
P2	Configuration RUN · [SET] · ESC	**RUN:** Operation mode, parameter settings cannot be changed **SET:** Configuration mode (device not in service, parameter settings can be changed, ⇨, ▚	See page 37
P3	Verify LCD segments 0000 to 9999	Read only	See section 8.2
P4*	Actuator type [ROT] · LIN · ESC	**ROT:** Rotary actuator **LIN:** Linear actuator **Note:** After initialization, this parameter is locked and can first be selected and changed after performing a reset to default settings (**P21**).	See section 8.3
P5*	Direction of action of actuator [PTO] · PTC · ESC	**PTO (power to open):** Fail-safe position = Valve CLOSED, 0 % of travel range Operating position = Valve OPEN, 100 % of travel range **PTC (power to close):** Fail-safe position = Valve OPEN, 100 % of travel range Operating position = Valve CLOSED, 0 % of travel range **Note:** Observe the assignment of contacts A and B depending on the direction of action (page page 79)! After initialization, this parameter is locked and can first be selected and changed after performing a reset to default settings (**P21**).	See section 8.4

No.	Parameter – Readings, values [default setting]	Description	
P6	Switching function of contacts A, B, C [NC] · NO NX1 … NX6 ESC	NC contact NO contact	See section 8.5
	Note: The contacts A, B and C can be individually configured in the TROVIS-VIEW software. This indicated on the display as NX1 … NX6. All the contacts are configured together as NC contact (1) or NO contact (2) by the local operation.		
P7*	Switching contact, lower end position 0.5 % to (P8 – 2.0 %) · ESC [2.0 %]	**The following applies:** PTO → Switching contact for fail-safe position PTC → Switching contact for operating position	See section 8.6
	Note: Observe the assignment of contacts A and B depending on the direction of action (page 79)!		
P8*	Switching contact, upper end position (P7 + 2.0 %) to 99.5 % · ESC [98.0 %]	**The following applies:** PTO → Switching contact for operating position PTC → Switching contact for fail-safe position	See section 8.6
	Note: Observe the assignment of contacts A and B depending on the direction of action (page 79)!		
P9*	Automatic initialization (INIT)	Starts initialization	See section 8.7.1
P10*	Manual initialization (INIT)	Initialization after manual confirmation of fail-safe position (POS1) and operating position (POS2)	See section 8.7.2
P11*	End position calibration	A calibration at the current position is performed.	See section 8.9
Status readout			
P12*	Status readout PST target range YES · [NO] · ESC	Issue status message F6/F7 if the valve moves to a position outside the PST target range ('PST step end' ± ½ 'PST tolerance band').	See section 9.2

No.	Parameter – Readings, values [default setting]	Description	
P13*	Status readout actuator transit time [OFF] · 0.5 to 1800.0 s · ESC	Issue status message F4 when the actuator exceeds the adjusted actuator transit time.	See section 9.5.1
Partial stroke test (PST) The PST step range is limited between 2 and 98 % ('PST step end' ± ½ 'PST tolerance band')			
P14*	PST step end 4.0 to 96.0 % · ESC [90.0 %]	Step end position that the valve is to be moved to during the PST. If the partial stroke test is not used, a third switching position can be indicated by contact C.	See section 9.2
P15*	PST tolerance band 4.0 to 96.0 % · ESC [10.0 %]	Tolerance added to the PST step end position. The partial stroke test has been completed successfully when the valve has reached the target range ('PST step end' ± ½ 'PST tolerance band') by one pulse, but not exceeded it.	See section 9.2
P16*	Start automatic PST [OFF] · 1 to 999 days · ESC	Interval between automatic partial stroke tests	See section 9.2
P17	Start manual PST	A single automatic partial stroke test is started.	See section 9.2
Locking function			
P18*	Lock operation [NO] · SSP · HMI · ESC	**HMI:** Locking of local operation (icon: 🔑) Only using TROVIS-VIEW! **SSP:** Locking of remote operation in TROVIS-VIEW. Only with local operation!	See section 9.1
Test functions			
P19*	Testing contacts A, B, B_LB, C, St ESC **Note:** B_LB on the display simulates a wire break according to NAMUR at contact B.	Checking of contacts A, B, C and St	See section 9.3
P20*	Testing solenoid valve	Solenoid valve de-energized (fail-safe position)	See section 9.4

No.	Parameter – Readings, values [default setting]	Description	
Reset function			
P21*	Reset RST · ESC	Resets all settings of electronic limit switch to the factory default settings.	See section 8.10
Display functions · Read only			
P22	Info: actuator transit time when solenoid valve is de-energized	Time [s] required by the actuator to move to the fail-safe position (dead time + transit time) Values determined during automatic initialization (P9)	–
P23	Info: actuator transit time when solenoid valve is energized	Time [s] required by the actuator to move to the operating position (dead time + transit time) Values determined during automatic initialization (P9)	–
P24	Info: temperature	Current operating temperature [°C] inside the electronic limit switch Keep ◎ pressed down –> reading in °F	–
P25	Info: operating hours	Number of operating hours	–
Rotary motions			
P26*	Max. rotary motions OFF · 100 to 9.9E7 · ESC [1.0E4]	Status message F2 is set when the max. number of rotary motions has been reached.	–
	Note: The monitoring of the rotary motions is deactivated by **P26** = OFF.		
P27*	Reset rotary motion counter RST · ESC	The unopened parameter indicates the number of rotary motions from one end position to the other. To reset the counter, open the parameter, select RST and confirm.	–
Firmware version			
P28	Info: firmware version	Current firmware version	–

13.1 Status messages

No.	Status message	Possible causes
Status messages marked with an asterisk (*) can be confirmed in SET configuration mode. See section 9.5.1.		
TROVIS-VIEW: Current status messages are saved with a time stamp in [Diagnostics – Status messages].		
F0	Stationary outside required/desired end positions	• Mechanical blockage • Supply pressure too low • External leakage **Recommended action** • Check attachment and supply air line.
F1	Left end position without being required to move	• Incorrect voltage supplied to the solenoid valve • Supply pressure too low • External leakage **Recommended action** • Check switching voltage to integrated/external solenoid valve. • Check supply air line.
F2	Limit of maximum rotary motion (P26) exceeded	The value entered in P26 for the maximum rotary motion has been exceeded. **Recommended action** • Deactivate function or enter higher value.
F3	Temperature limits exceeded	The temperature in the electronic limit switch is too low/too high. **Recommended action** • Check the operating conditions.
F4*	Actuator transit time exceeded	The actuator transit time has exceeded the limit entered in P13. **Recommended action** • Check attachment. • Enter a higher limit. **Note:** The status message is only generated when P13 ≠ OFF.

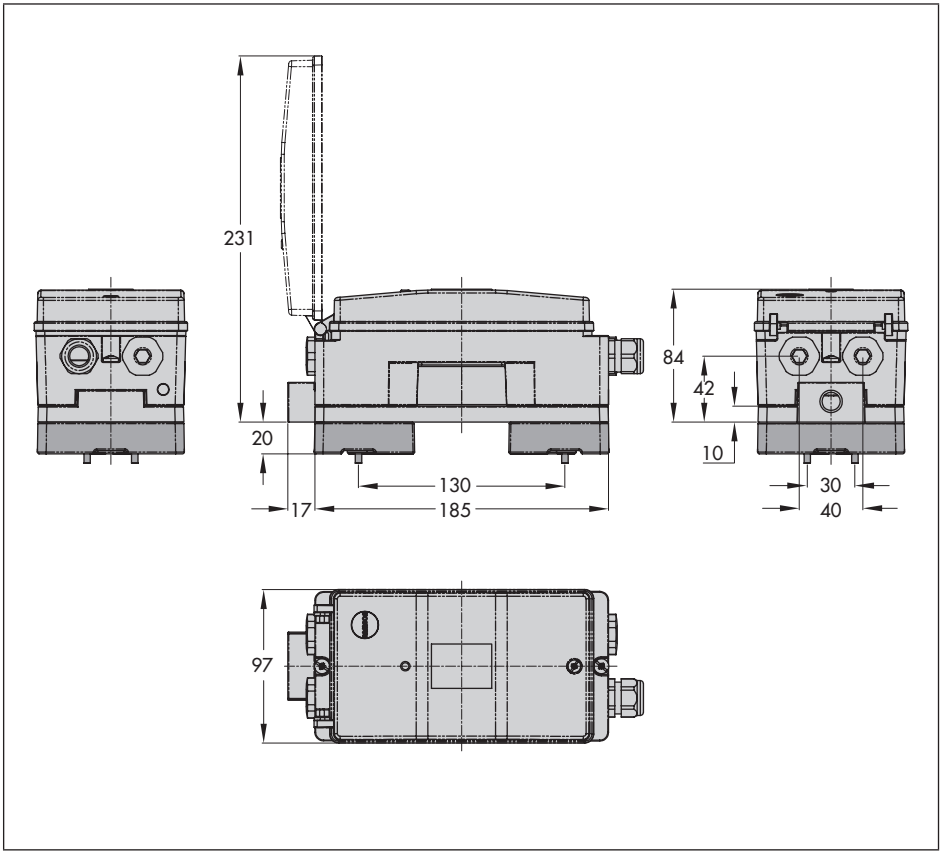
No.	Status message	Possible causes
F5*	Actuator stationary when required to move	• Mechanical blockage • Supply pressure too low • External leakage **Recommended action** • Check attachment and supply air line.
	Note: If the valve moves after a delay, F5 remains active until the next successful switching demand.	
Partial stroke test (PST)		
F6* **F7***	Min. value for PST not reached Max. value for PST exceeded	• Mechanical blockage • Friction too high • Supply pressure too low **Recommended action** • Check attachment and supply air line. • Check valve.
	Note: The status messages are only generated when P12 = YES.	
F8*	No switching voltage during PST	• Incorrect voltage supplied to the solenoid valve • Breakage of wire to external solenoid valve **Recommended action** • Check switching voltage to integrated/external solenoid valve.
	Note: It is only evaluated when the partial stroke test is started manually (P17).	
F9*	Time-out during PST	• Mechanical blockage • Supply pressure too low • External leakage **Recommended action** • Check attachment and supply air line.
Error messages		
F10	Error E0 to E10 exists	See section 13.2.

13.2 Error messages

No.	Error message	Possible causes
Error messages marked with an asterisk (*) can be confirmed in SET configuration mode. See section 9.5.2.		
TROVIS-VIEW: The last 32 error messages are displayed with a time stamp in [Diagnostics – Logging of device errors].		
E0	Positioner not initialized	• The electronic limit switch has not yet been initialized. **Recommended action** • Start initialization with P9 or P10 parameter.
E1*	INIT: actuator does not move	• Mechanical blockage • Supply pressure too low • External leakage • Incorrect voltage supplied to the solenoid valve **Recommended action** • Check attachment and supply air line. • Check switching voltage to integrated/external solenoid valve.
E2*	INIT: min. travel not reached	• Mechanical blockage • Supply pressure too low • External leakage **Recommended action** • Check attachment and supply air line. • Increase angle of rotation at the actuator.
E3*	INIT: max. travel exceeded	• Maximum angle exceeds 170°. **Recommended action** • Reduce angle of rotation at the actuator.
E4*	INIT: actuator travels too fast	• K_V coefficient of solenoid valve too high **Recommended action** • Install a restriction. • Version for external solenoid valve: Reduce K_V coefficient at solenoid valve.

No.	Error message	Possible causes
E5*	INIT: no switching voltage applied	• Incorrect voltage supplied to the solenoid valve • Forced venting active during initialization **Recommended action** • Check switching voltage to integrated/external solenoid valve. • Check forced venting input.
E6*	INIT: time-out	• Supply pressure too low • Friction too high • K_V coefficient of solenoid valve too low **Recommended action** • Check attachment and supply air line. • Version for external solenoid valve: Use a different solenoid valve with a higher K_V coefficient.
E7*	Function canceled	• Internal error **Recommended action** • Repeat function/initialization.
E8*	Unable to calibrate end positions	• The end stops have shifted by 10° at the minimum. **Recommended action** • Re-initialize the electronic limit switch.
Device error		
E9*	Device error 1	• Internal error **Recommended action** • Restart the electronic limit switch (return it to SAMSON if error repeatedly occurs).
	Note: When E9 is generated, the wire break (contact B_LB) is additionally signaled in accordance with IEC 60947-5-6.	
E10*	Device error 2	• Internal error **Recommended action** • The electronic limit switch should be replaced soon. The device still functions.

14 Dimensions in mm



[Translation of German original]

Physikalisch- Technische Bundesanstalt
Braunschweig and Berlin

]

(1) **EC Type Examination Certificate**

(2) Equipment and Protective Systems Intended for Use in Potentially Explosive Atmospheres – Directive 94/9/EC

(3) EC type examination certificate number

PTB 08 ATEX 2039 X

(4) Equipment: Type 3738-..-110.. Electronic Valve Position Monitor

(5) Manufacturer: SAMSON AG Mess- und Regeltechnik

(6) Address: Weismüllerstraße 3, 60314 Frankfurt am Main, Germany

(7) This equipment and any acceptable variation thereto are specified in the schedule to this certificate and the documents therein referred to.

(8) Physikalisch-Technische Bundesanstalt, notified body no. 0102 in accordance with Article 9 of the Council Directive 94/9/EC of 23 March 1994, certifies that this equipment has been found to comply with the essential health and safety requirements relating to the design and construction of equipment and protective systems intended for use in potentially explosive atmospheres, given in Annex II to the Directive.
The examination and test results are recorded in the confidential Assessment and Test Report **PTB Ex 09-28163**.

(9) Compliance with the essential health and safety requirements has been assured by compliance with:

EN 60079-0:2006	**EN 61241-0:2006**
EN 60079-11:2007	**EN 61241-11:2006**

(10) If the sign "X" is placed after the certificate number, it indicates that the equipment is subject to special conditions for safe use specified in the schedule to this certificate.

(11) This EC type examination certificate relates only to the design and construction of the specified equipment or protective system in accordance with Directive 94/9/EC. Further requirements of this Directive apply to the manufacture and supply of this equipment. These requirements are not covered by this certificate.

**EC type examination certificates without signature nor seal are invalid.
This EC type examination certificates may only be reproduced without changes.
Excerpts or modifications are to be approved by Physikalisch-Technische Bundesanstalt.**

Physikalisch-Technische Bundesanstalt · Bundesallee 100 · 38116 Braunschweig · Germany

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Physikalisch- Technische Bundesanstalt
Braunschweig and Berlin

(12) The marking of the equipment shall include the following:

Ex II 2G Ex ia IIC T6 or II 2D Ex iaD 21 T80 °C

Certification Sector for Explosion Protection Braunschweig, 16 March 2009
O/o

[Signature Johannsmeyer, stamp: Physikalisch-Technische Bundesanstalt 56]

Dr.-Ing. U. Johannsmeyer
Director and Professor

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Physikalisch-Technische Bundesanstalt
Braunschweig and Berlin

(13) **Enclosure**

(14) **EC Type Examination Certificate PTB 08 ATEX 2039 X**

(15) **Description of the equipment or protective system:**

The Type 3738-..-110.. Electronic Valve Position Monitor is designed to safely indicate the end positions of on/off control valves and includes different diagnostic functions for safe valve operation. The valve monitor in type of protection Ex ia IIC T6 is used for connection to intrinsically safe NAMUR contacts with intrinsically safe internal or external solenoid valves.
The valve monitor is intended for use in hazardous areas.
The following table lists the relation between equipment type, type of protection, temperature class and permissible ambient temperature range:

Type	Type of protection	Temperature class	Permissible ambient temperature range
3738-..110..	Ex ia IIC	T6	–40 °C to 55 °C
		T5	–40 °C to 70 °C
		T4	–40 °C to 80 °C

Electric data

Supply current circuit
using limit switch (A) NAMUR contact .....in type of protection Ex ia IIC
(terminals 41/42) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 20 V
I_i = 60 mA
P_i = 400 mW
L_i negligibly small
C_i = 5 nF

Limit switches (B/C) NAMUR contact.....in type of protection Ex ia IIC
(terminals 51/52 or 61/62) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 20 V
I_i = 60 mA
P_i = 400 mW
L_i negligibly small
C_i = 15 nF

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Schedule to the EC Type Examination Certificate PTB 08 ATEX 2039 X

Limit switch (status).....in type of protection Ex ia IIC
(terminals 83/84) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 20 V
I_i = 60 mA
P_i = 400 mW
L_i negligibly small
C_i = 15 nF

Version 3738-..-110.4..
Internal solenoid valve.....in type of protection Ex ia IIC
(terminals 81/82 external operating voltage) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 28 V
I_i = 115 mA
or
U_i = 32 V
I_i = 87.6 mA
L_i negligibly small
C_i = 5 nF

Version 3738-..-110.0..
External solenoid valve.....in type of protection Ex ia IIC
(terminals 81/82 external operating voltage) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 28 V
I_i = 115 mA
or
U_i = 32 V
I_i = 87.6 mA
L_i negligibly small
C_i = 5 nF
or

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Schedule to the EC Type Examination Certificate PTB 08 ATEX 2039 X

(terminals 281/282 external solenoid valve) .....in type of protection Ex ia IIC

U_0 = 28 V
I_0 = 115 mA

or

U_0 = 32 V
I_0 = 87.6 mA
P_0 = 1 W

Linear characteristic

L_i negligible small
C_i = 5 nF
L_0 = 3 mH
C_0 = 56 nF

Observe the rules governing the interconnection of intrinsically safe current circuits (if applicable) and ensure that the application range is observed.

SSP interface .....in type of protection Ex ia IIC
(connector) For connection to a certified intrinsically safe current circuit only

Max. values:

U_i = 20 V
I_i = 60 mA
P_i = 200 mW

L_i negligibly small
C_i negligibly small

or
in type of protection Ex ia IIC

U_0 = 9.55 V
I_0 = 32 mA
P_0 = 147 mW

Linear characteristic

L_i negligibly small
C_i negligibly small
L_0 = 10 mH
C_0 = 640 nF

Observe the rules governing the interconnection of intrinsically safe current circuits (if applicable) and ensure that the application range is observed.

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Schedule to the EC Type Examination Certificate PTB 08 ATEX 2039 X

(16) **Assessment and Test Report PTB Ex 09-28163**

(17) **Special conditions for safe use**

To prevent the risk of electrostatic charging, mark the plastic part of the enclosure with appropriate warning instructions.
Observe the mounting instructions wherever it is necessary to protect the equipment against mechanical influences.

(18) **Essential health and safety requirements**

Compliance with the essential health and safety requirements has been assured by compliance with the standards mentioned above.

Certification Sector for Explosion Protection Braunschweig, 16 March 2009
O/o

[Signature Johannsmeyer, stamp: Physikalisch-Technische Bundesanstalt 56]

Dr.-Ing. U. Johannsmeyer
Director and Professor

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1st ADDENDUM
according to Directive 94/9/EC, Annex III, Clause 6
to EC Type Examination Certificate PTB 08 ATEX 2039 X

Equipment: Type 3738-..-310.. Electronic Limit Switch

Marking: II 2G Ex e [ia] IIC T4 or II 2D Ex tD A21 IP 66 T80 °C

Manufacturer: SAMSON AG Mess- und Regeltechnik

Address: Weismüllerstr. 3, D-60314 Frankfurt, Germany

Description of additions and modifications

The Type 3738-..-110.. Electronic Limit Switch is expanded by the Type 3738-..-310..
The Type 3738-..-310.. is used for connection to external, intrinsically safe NAMUR contacts and to non-intrinsically safe solenoid valves in types of protection Ex d e, Ex e or Ex e mb.

The limit switch is intended for use in hazardous areas.

The following table lists the relation between equipment type, type of protection, temperature class and permissible ambient temperature range:

Type	Type of protection	Temperature class	Permissible ambient temperature range
3738-..-110..	Ex ia IIC	T6	–40 °C to 55 °C
		T5	–40 °C to 70 °C
		T4	–40 °C to 80 °C
3738-..-310..	Ex e [ia] IIC	T4	–40 °C to 80 °C

Electric data

Voltage supply ..... Max. values:
(terminals 81/82)

U = 24V DC
U_m = 60V
P = 18W

External solenoid valve ..... Max. values:
(terminals 281/282)

U = 24V DC
U_m = 60V
P = 18W

Supply current circuit
using limit switch (A) NAMUR contact ..... in type of protection Ex ia IIC
(terminals 41/42) For connection to a certified intrinsically safe current circuit only

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1st Addendum to EC Type Examination Certificate PTB 08 ATEX 2039 X

Max. values:

U_i = 20V
I_i = 60mA
P_i = 400mW
L_i negligibly small
C_i = 5nF

Limit switches (B/C) NAMUR contact ..... in type of protection Ex ia IIC
(terminals 51/52 or 61/62) ..... For connection to a certified intrinsically safe current circuit only

..... Max. values:

..... U_i = 20V
..... I_i = 60mA
..... P_i = 400mW
..... L_i negligibly small
..... C_i = 15nF

Limit switch (status)..... in type of protection Ex ia IIC
(terminals 83/84) For connection to a certified intrinsically safe current circuit only

Max. values:

..... U_i = 20V
..... I_i = 60mA
..... P_i = 400mW
..... L_i negligibly small
..... C_i = 15nF

Applied standards

EN 60079-0:2006 EN 60079-7:2007 EN 61241-0:2006
EN 60079-11:2007 EN 61241-1:2004

Assessment and Test Report PTB Ex 09-29233

Certification Sector for Explosion Protection Braunschweig, 20 October 2009
O/o
[Signature Gerlach, stamp: Physikalisch-Technische Bundesanstalt 56]
Dr.-Ing. U. Gerlach
Oberregierungsrat [senior government official]

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PTB

2nd ADDENDUM
according to Directive 94/9/EC, Annex III, Clause 6
to EC Type Examination Certificate PTB 08 ATEX 2039 X

Equipment: Type 3738-..-110.., Type 3738-..-310.. and Type 3738-..-810..
Electronic Limit Switch

Marking: **II 2 G Ex ia IIC T6 and II 2 D Ex ia IIIC T80 °C IP 66 or**
II 2 G Ex eb [ia] IIC T4 and II 2 D Ex tb IIIC T80 °C IP 66 or
II 3 G Ex ic IIC T4 and II 3 G Ex nA II T4 Gc and
II 3 D Ex tc IIIC T80 °C IP 66

Manufacturer: SAMSON AG, Mess- und Regeltechnik

Address: Weismüllerstraße 3, 60314 Frankfurt, Germany

Description of additions and modifications

The Type 3738-..-110.. and Type 3738-..-310.. Electronic Limit Switches are expanded by the Type 3738-..-810..
The Type 3738-..-810.. in type of protection Ex ic or Ex nA is used to energize external solenoid valves. The limit switch is intended for use in hazardous areas of zone 2 or 22.

The following table lists the relation between equipment type, type of protection, temperature class and permissible ambient temperature range:

Type	Type of protection	Temperature class	Permissible ambient temperature range
3738-..-110..	Ex ia IIC	T6	–40 °C to 55 °C
		T5	–40 °C to 70 °C
		T4	–40 °C to 80 °C
3738-..-310..	Ex eb [ia] IIC	T4	–40 °C to 80 °C
3738-..-810..	Ex ic IIC or Ex nA II	T4	–40 °C to 80 °C

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PTB

2nd Addendum to EC Type Examination Certificate PTB 08 ATEX 2039 X

Electric data

Voltage supply ..... in type of protection Ex ic IIC
(terminals 81/82)

Max. values:

U_i = 32 V DC
I_i = 100 mA
C_i = 5 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 24 V
U_m = 60 V

Supply current circuit ..... in type of protection Ex ic IIC
using limit switch (A) NAMUR contact
(terminals 41/42)

Max. values:

U_i = 32 V DC
I_i = 100 mA
C_i = 5 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 8 V
R_i = 1 kΩ (EN 60947-5-6)

Limit switches (B/C) NAMUR contacts ..... in type of protection Ex ic IIC
(terminals 51/52 or 61/62)

Max. values per limit switch:

U_i = 20 V DC
I_i = 60 mA
C_i = 15 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 8 V
R_i = 1 kΩ (EN 60947-5-6)

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2nd Addendum to EC Type Examination Certificate PTB 08 ATEX 2039 X

Limit switches (status) ..... in type of protection Ex ic IIC
(terminals 83/84)

Max. values:

U_i = 20 V DC
I_i = 60 mA
C_i = 15 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 8 V
R_i = 1 kΩ (EN 60947-5-6)

External solenoid valve ..... in type of protection Ex ic IIC
(terminals 281/282)

Max. values:

U_0 = 32 V DC
I_0 = 100 mA
Linear characteristic
C_0 = 56 nF
L_0 = 3 mH
C_i = 5 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 24 V
U_m = 60 V

Observe the rules governing the interconnection of intrinsically safe current circuits (if applicable) and ensure that the application range is observed.

SSP interface ..... in type of protection Ex ic IIC
(connector)

Max. values:

U_i = 20 V DC
I_i = 60 mA
C_i negligibly small
L_i negligibly small

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Physikalisch-Technische Bundesanstalt
Braunschweig and Berlin

2nd Addendum to EC Type Examination Certificate PTB 08 ATEX 2039 X

or

U_0 = 9.55 V DC
I_0 = 32 mA
P_0 = 147 mW
Linear characteristic
C_0 = 640 nF
L_0 = 10 mH
C_i = 5 nF
L_i negligibly small

or
in type of protection Ex nA II
Operating values:

U_B = 8 V
I_B = 20 mA

Observe the rules governing the interconnection of intrinsically safe current circuits (if applicable) and ensure that the application range is observed.

The special conditions and all specifications of the EC type examination certificate remain valid without changes.

Applied standards

EN 60079-0:2009 **EN 60079-7:2007** **EN 60079-11:2007** **EN 60079-31:2009**

Assessment and Test Report PTB Ex 12-21067

Certification Sector for Explosion Protection Braunschweig, 2 February 2012
O/o

[Signature Johannsmeyer, stamp: Physikalisch-Technische Bundesanstalt 24]

Dr.-Ing. U. Johannsmeyer
Director and Professor

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Pth54 Add-2.doc

Index

A

Accessories 18
Actuator type 39
Article code 7
Attachment
  accessories 18
  to linear actuators 19
  to rotary actuators 22

C

Cable entry 30
Calibration 55
Communication
  TROVIS-VIEW 12
Connections
  electric 29
  pneumatic 28
Contacts
  technical data 15
  testing 53

D

Design 8
Direction of action 8
Display
  adapt 38
  device initialized 38
  device not yet initialized 38
  verifying readings 38

E

End position calibration 44
Error messages 54, 63

F

Fault 54
Firmware update 56

I

Initialization
  automatic 42
  manual 43

L

Limit contacts 40

M

Maintenance 55

O

Operating structure 34
Operation 46
  lock 46
Operator controls 33

P

Parameter list 57
Partial stroke testing 46

R

Replacing electronic limit switch 44
Reset to default settings 45
Rotary pushbutton 33

S

Safety instructions 6
Safety-related information 12
Servicing 56
Solenoid valve
  technical data 16
  testing 53
SSP interface 33
Start-up 38
Status messages 54, 61

Supply 28
Supply pressure 28
Switching function of contacts 40

T

Technical data
electronic limit switch 14
solenoid valve 16
Testing contacts 53
Testing solenoid valve 53

W

Wire break 30

Z

Zero calibration 44

Key code 42

Parameter list	
P0	Info: actual value
P1	Reading direction
P2	Configuration: RUN/SET
P3	Verify LCD segments
P4*	Actuator type
P5*	Actuator's direction of action
P6*	Switching function of contacts A, B, C
P7*	Switching contact, lower end position
P8*	Switching contact, upper end position
P9*	Automatic initialization
P10*	Manual initialization
P11*	End position calibration
P12*	Status readout PST target range
P13*	Status readout of actuator transit time
P14*	PST step end
P15*	PST tolerance band
P16*	Start automatic PST
P17*	Start manual PST
P18*	Lock operation
P19*	Testing contacts A, B, B_LB, C, St
P20*	Testing solenoid valve
P21*	Reset
P22	Info: actuator transit time when solenoid valve is de-energized
P23	Info: actuator transit time when solenoid valve is energized
P24	Info: temperature
P25	Info: operating hours
P26*	Max. rotary motions
P27*	Reset rotary motion counter
P28	Info: firmware version

Status messages	
F0	Stationary outside required/desired end positions
F1	Left end position without being required to move
F2	Limit of P26 exceeded
F3	Temperature limits exceeded
F4	Actuator transit time exceeded
F5	Actuator stationary when required to move
F6	Min. value for PST not reached
F7	Max. value for PST exceeded
F8	No switching voltage during PST
F9	Time-out during PST
F10	Error E0 to E10 exists

Error messages	
E0	No initialization
E1	INIT: actuator does not move
E2	INIT: min. travel not reached
E3	INIT: max. travel exceeded
E4	INIT: actuator travels too fast
E5	INIT: no switching voltage applied
E6	INIT: time-out
E7	Function canceled
E8	Unable to calibrate end positions
E9	Device error 1
E10	Device error 2

The parameters/errors marked with an asterisk (*) can only be changed/confirmed in the SET configuration mode.

Assignment based on the direction of action

PTO (power to open)

	+	–	Position	Switching contact for end position
Contact A	41	42	Fail-safe position (0 %) · Valve CLOSED	**P7** (0.5 to 96.0 %, [2.0 %])
Contact B	51	52	Operating position (100 %) · Valve OPEN	**P8** (4.0 to 99.5 %, [98.0 %])

PTC (power to close)

	+	–	Position	Switching contact for end position
Contact A	51	52	Fail-safe position (100 %) · Valve OPEN	**P8** (4.0 to 99.5 %, [98.0 %])
Contact B	41	42	Operating position (0 %) · Valve CLOSED	**P7** (0.5 to 96.0 %, [2.0 %])

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